

## Engines

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# Contents



# Chapter 1

## Module Index

### 1.1 Modules

Here is a list of all modules:

Connection_mesh . . . . .	??
Engine_methods . . . . .	??
Engine_parameters . . . . .	??
Well_controls . . . . .	??



## Chapter 2

# Hierarchical Index

### 2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

block_perf . . . . .	??
block_well . . . . .	??
conn_mesh . . . . .	??
engine_base . . . . .	??
engine_base_gpu . . . . .	??
engine_elasticity_cpu< ND > . . . . .	??
engine_pm_cpu . . . . .	??
gpu_simulator . . . . .	??
gpu_simulator_nc3 . . . . .	??
pm::Face . . . . .	??
pm::pm_discretizer::Gradients . . . . .	??
pm::pm_discretizer::InnerMatrices . . . . .	??
linalg::Matrix< T > . . . . .	??
linalg::Matrix< value_t > . . . . .	??
pm::Matrix33 . . . . .	??
pm::Stiffness . . . . .	??
pm::mech_operators . . . . .	??
ms_well . . . . .	??
operator_set_evaluator_iface	
operator_set_gradient_evaluator_iface	
interpolator_base . . . . .	??
linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS > . . . . .	??
linear_adaptive_cpu_interpolator< index_t, N_DIMS, N_OPS > . . . . .	??
linear_static_cpu_interpolator< index_t, N_DIMS, N_OPS > . . . . .	??
multilinear_interpolator_base< index_t, value_t, N_DIMS, N_OPS > . . . . .	??
multilinear_adaptive_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS > . . . . .	??
multilinear_gpu_interpolator_base< index_t, value_t, N_DIMS, N_OPS > . . . . .	??
multilinear_static_gpu_interpolator2< index_t, value_t, N_DIMS, N_OPS > . . . . .	??
multilinear_static_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS > . . . . .	??
multilinear_adaptive_cpu_interpolator< idx_type, val_type, N_DIMS, N_OPS > . . . . .	??
multilinear_static_cpu_interpolator< interp_value_t, N_DIMS, N_OPS > . . . . .	??
multilinear_static_gpu_interpolator< interp_value_t, N_DIMS, N_OPS > . . . . .	??
py_operator_set_evaluator_iface . . . . .	??
pm::pm_discretizer . . . . .	??

property_evaluator_iface . . . . .	??
py_property_evaluator_iface . . . . .	??
sim_params . . . . .	??
sim_stat . . . . .	??
well_control . . . . .	??
well_control_iface . . . . .	??
bhp_inj_well_control . . . . .	??
bhp_prod_well_control . . . . .	??
gt_bhp_prod_well_control . . . . .	??
gt_bhp_temp_inj_well_control . . . . .	??
gt_mass_rate_enthalpy_inj_well_control . . . . .	??
gt_mass_rate_prod_well_control . . . . .	??
gt_rate_prod_well_control . . . . .	??
gt_rate_temp_inj_well_control . . . . .	??
rate_inj_well_control . . . . .	??
rate_inj_well_control_mass_balance . . . . .	??
rate_prod_well_control . . . . .	??
rate_prod_well_control_mass_balance . . . . .	??

## Chapter 3

# Class Index

### 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">bhp_inj_well_control</a>	BHP control for injection compositional well . . . . .	??
<a href="#">bhp_prod_well_control</a>	BHP control for production compositional well . . . . .	??
<a href="#">block_perf</a>	Structure for well perforation . . . . .	??
<a href="#">block_well</a>	Class for well definition (both segments and controls) . . . . .	??
<a href="#">conn_mesh</a>	This class defines mesh and corresponding arrays . . . . .	??
<a href="#">engine_base</a>	This class defines infrastructure for simulation . . . . .	??
<a href="#">engine_base_gpu</a>	This class defines infrastructure for simulation . . . . .	??
<a href="#">engine_elasticity_cpu&lt; ND &gt;</a>	. . . . .	??
<a href="#">engine_pm_cpu</a>	. . . . .	??
<a href="#">pm::Face</a>	. . . . .	??
<a href="#">gpu_simulator</a>	. . . . .	??
<a href="#">gpu_simulator_nc3</a>	. . . . .	??
<a href="#">pm::pm_discretizer::Gradients</a>	. . . . .	??
<a href="#">gt_bhp_prod_well_control</a>	BHP control for production geothermal well . . . . .	??
<a href="#">gt_bhp_temp_inj_well_control</a>	BHP and temperature control for injection geothermal well . . . . .	??
<a href="#">gt_mass_rate_enthalpy_inj_well_control</a>	Mass rate and enthalpy control for injection geothermal well . . . . .	??
<a href="#">gt_mass_rate_prod_well_control</a>	Mass rate control for production geothermal well . . . . .	??
<a href="#">gt_rate_prod_well_control</a>	Volumetric rate control for production geothermal well . . . . .	??
<a href="#">gt_rate_temp_inj_well_control</a>	Volumetric rate and temperature control for injection geothermal well . . . . .	??
<a href="#">pm::pm_discretizer::InnerMatrices</a>	. . . . .	??
<a href="#">interpolator_base</a>	. . . . .	??
<a href="#">linear_adaptive_cpu_interpolator&lt; index_t, N_DIMS, N_OPS &gt;</a>	. . . . .	??

<a href="#">linear_cpu_interpolator_base&lt; index_t, N_DIMS, N_OPS &gt;</a>	
Interpolator base for static/adaptive piecewise linear interpolator	??
<a href="#">linear_static_cpu_interpolator&lt; index_t, N_DIMS, N_OPS &gt;</a>	??
<a href="#">linalg::Matrix&lt; T &gt;</a>	??
<a href="#">pm::Matrix33</a>	??
<a href="#">pm::mech_operators</a>	??
<a href="#">ms_well</a>	
Base class for multi-segmented well	??
<a href="#">multilinear_adaptive_cpu_interpolator&lt; idx_type, val_type, N_DIMS, N_OPS &gt;</a>	??
<a href="#">multilinear_adaptive_cpu_interpolator2&lt; index_t, value_t, N_DIMS, N_OPS &gt;</a>	
Piecewise multilinear interpolator with adaptive storage	??
<a href="#">multilinear_gpu_interpolator_base&lt; index_t, value_t, N_DIMS, N_OPS &gt;</a>	
Piecewise multilinear GPU interpolator base class	??
<a href="#">multilinear_interpolator_base&lt; index_t, value_t, N_DIMS, N_OPS &gt;</a>	
Interpolator base for static/adaptive piecewise multilinear interpolator	??
<a href="#">multilinear_static_cpu_interpolator&lt; interp_value_t, N_DIMS, N_OPS &gt;</a>	??
<a href="#">multilinear_static_cpu_interpolator2&lt; index_t, value_t, N_DIMS, N_OPS &gt;</a>	
Piecewise multilinear interpolator with static storage	??
<a href="#">multilinear_static_gpu_interpolator&lt; interp_value_t, N_DIMS, N_OPS &gt;</a>	??
<a href="#">multilinear_static_gpu_interpolator2&lt; index_t, value_t, N_DIMS, N_OPS &gt;</a>	
Piecewise multilinear interpolator with static storage	??
<a href="#">pm::pm_discretizer</a>	??
<a href="#">property_evaluator_iface</a>	
Virtual interface class for evaluation of physical properties values Implemented mainly by different C++ physical kernels from darts.physics However, pure Python implementation is also possible through inheritance	??
<a href="#">py_operator_set_evaluator_iface</a>	??
<a href="#">py_property_evaluator_iface</a>	??
<a href="#">rate_inj_well_control</a>	
Volumetric rate control for injection compositional well	??
<a href="#">rate_inj_well_control_mass_balance</a>	
Rate control based on mass balance equation for injection compositional well	??
<a href="#">rate_prod_well_control</a>	
Volumetric rate control for production compositional well	??
<a href="#">rate_prod_well_control_mass_balance</a>	
Rate control based on mass balance equation for production compositional well	??
<a href="#">sim_params</a>	
Main simulation parameters including tolerances	??
<a href="#">sim_stat</a>	
Main simulation statistics with active and wasted counts	??
<a href="#">pm::Stiffness</a>	??
<a href="#">well_control</a>	
Structure for well control	??
<a href="#">well_control_iface</a>	
Base class work well control/constraint	??

## Chapter 4

# Module Documentation

### 4.1 Connection\_mesh

#### Functions

- int `conn_mesh::init` (std::string conn2p\_filename)  
*init mesh by reading TPFACONNS keyword file*
- int `conn_mesh::init` (std::vector< index\_t > &block\_m, std::vector< index\_t > &block\_p, std::vector< value\_t > &tran, std::vector< value\_t > &tranD)  
*init mesh by reading array of left/right neighbours*
- int `conn_mesh::init_mpfa` (std::vector< index\_t > &block\_m, std::vector< index\_t > &block\_p, std::vector< index\_t > &fstencil, std::vector< index\_t > &fst\_offset, std::vector< value\_t > &ftran, std::vector< value\_t > &rhs, uint8\_t \_n\_dim, index\_t \_n\_matrix, index\_t \_n\_bounds)  
*init mesh by reading MPFA connections*
- int `conn_mesh::init_mpsa` (std::vector< index\_t > &block\_m, std::vector< index\_t > &block\_p, std::vector< index\_t > &sstencil, std::vector< index\_t > &sst\_offset, std::vector< value\_t > &stran, uint8\_t \_n\_dim, index\_t \_n\_matrix, index\_t \_n\_bounds, index\_t \_n\_fracs)  
*init mesh by reading MPSA connections*
- int `conn_mesh::init_pm` (std::vector< index\_t > &block\_m, std::vector< index\_t > &block\_p, std::vector< index\_t > &stencil, std::vector< index\_t > &st\_offset, std::vector< value\_t > &tran, std::vector< value\_t > &rhs, std::vector< value\_t > &tran\_biot, std::vector< value\_t > &rhs\_biot, index\_t \_n\_matrix, index\_t \_n\_bounds, index\_t \_n\_fracs)  
*init mesh by reading both MPFA and MPSA connections*
- int `conn_mesh::init_const_1d` (double trans\_const, index\_t nb)  
*init mesh for 1D reservoir with 'nb' blocks*
- int `conn_mesh::add_conn` (index\_t block\_m, index\_t block\_p, value\_t trans)  
*add a new connection to connection list*
- int `conn_mesh::add_conn_mpfa` (index\_t block\_m, index\_t block\_p, value\_t trans)
- int `conn_mesh::reverse_and_sort` ()  
*reverse connections and sort them by both row and col*
- int `conn_mesh::reverse_and_sort_dvel` ()  
*reverse connections and renumerate velocity mappers and sort them by both row and col*
- int `conn_mesh::reverse_and_sort_mpfa` ()  
*reverse mpsa connections and sort them by both row and col*

- int `conn_mesh::reverse_and_sort_mpsa` ()
- int `conn_mesh::reverse_and_sort_pm` ()
- int `conn_mesh::add_wells` (std::vector< `ms_well` \*> &wells)  
*discretize ms wells into reservoir*
- int `conn_mesh::add_wells_mpfa` (std::vector< `ms_well` \*> &wells)

## Variables

- std::vector< index\_t > `conn_mesh::block_m`  
*[n\_conns] array of indices of blocks on the minus side of a connection (smaller index)*
- std::vector< index\_t > `conn_mesh::block_p`  
*[n\_conns] array of indices of blocks on the plus side of a connection (bigger index)*
- std::vector< value\_t > `conn_mesh::tran`  
*[n\_conns] array of transmissibility values for given connection*
- std::vector< value\_t > `conn_mesh::tranD`  
*[n\_conns] array of diffusion transmissibility values for given connection (transmis value)*
- std::vector< value\_t > `conn_mesh::grav_coef`  
*[n\_conns] array of gravity coefficient for every connection ( = (depth[block\_m] - depth[block\_p]) \* g)*
- std::vector< value\_t > `conn_mesh::velocity`  
*[n\_conns] array of initial velocity values (Decouple - velocity engine)*
- std::vector< value\_t > `conn_mesh::tran_const`  
*[n\_conns] array of temporary const transmissibilities*
- uint8\_t `conn_mesh::n_vars`  
*Number of unknowns per block.*
- std::vector< index\_t > `conn_mesh::fstencil`  
*array of indices of blocks are neccessary for each connection*
- std::vector< index\_t > `conn_mesh::fst_offset`  
*[n\_conns + 1] array of offsets of the first block of connection in 'stencil'*
- std::vector< index\_t > `conn_mesh::sstencil`  
*array of indices of blocks are neccessary for each connection*
- std::vector< index\_t > `conn_mesh::sst_offset`  
*[n\_conns + 1] array of offsets of the first block of connection in 'stencil'*
- std::vector< value\_t > `conn_mesh::stran`  
*[n\_conns] array of transmissibility values for given connection*
- std::vector< value\_t > `conn_mesh::stran_biot`  
*[n\_conns] array of transmissibility values for biot contribution to the given connection*
- std::vector< std::vector< int > > `conn_mesh::stencil`
- std::vector< value\_t > `conn_mesh::rhs`
- std::vector< value\_t > `conn_mesh::rhs_biot`
- std::vector< value\_t > `conn_mesh::f`
- index\_t `conn_mesh::n_links`  
*number of non-zero links*
- std::vector< value\_t > `conn_mesh::volume`  
*[n\_blocks] array of volumes of mesh blocks*
- std::vector< value\_t > `conn_mesh::poro`  
*[n\_blocks] array of porosities of mesh blocks*
- std::vector< value\_t > `conn_mesh::depth`  
*[n\_blocks] array of depths*
- std::vector< value\_t > `conn_mesh::heat_capacity`  
*[n\_blocks] array of heat capacity of rock*

- `std::vector< value_t > conn_mesh::rock_cond`  
*[n\_blocks] array of heat conduction of rock;*
- `std::vector< value_t > conn_mesh::kin_factor`  
*[n\_blocks] array of kinetic rate constants (dependent on the initial porosity and other factors!);*
- `std::vector< value_t > conn_mesh::pressure`  
*[n\_blocks] array of initial pressure values*
- `std::vector< value_t > conn_mesh::composition`  
*[n\_blocks] array of initial composition values*
- `std::vector< value_t > conn_mesh::temperature`  
*[n\_blocks] array of initial temperature values*
- `std::vector< value_t > conn_mesh::enthalpy`  
*[n\_blocks] array of initial enthalpy values*
- `std::vector< value_t > conn_mesh::displacement`  
*[n\_dim \* n\_blocks] array of initial displacements values*
- `std::vector< value_t > conn_mesh::bc`  
*[(1 + n\_dim) \* n\_bounds] array of boundary conditions*
- `std::vector< value_t > conn_mesh::bc_prev`  
*[(1 + n\_dim) \* n\_bounds] array of boundary conditions*
- `std::vector< value_t > conn_mesh::pz_bounds`  
*[nc \* n\_bounds] array of pressures and (inflow) fractions at boundaries*
- `std::vector< value_t > conn_mesh::biot`  
*[9 \* n\_blocks] array of biot coefficients of mesh blocks*
- `std::vector< value_t > conn_mesh::drained_compressibility`  
*[n\_blocks] array of drained compressibility of mesh blocks*
- `std::vector< index_t > conn_mesh::op_num`  
*[n\_blocks] array of operator set index for every block*

#### 4.1.1 Detailed Description

Parameters and methods in mesh class exposed to Python

#### 4.1.2 Function Documentation

##### 4.1.2.1 reverse\_and\_sort\_mpfa()

```
int conn_mesh::reverse_and_sort_mpfa ( )
```

reverse mpsa connections and sort them by both row and col

[n\_blocks] map of connections [block\_p, conn\_idx] per block

##### 4.1.2.2 reverse\_and\_sort\_mpsa()

```
int conn_mesh::reverse_and_sort_mpsa ( )
```

[n\_blocks] map of connections [block\_p, conn\_idx] per block

##### 4.1.2.3 reverse\_and\_sort\_pm()

```
int conn_mesh::reverse_and_sort_pm ( )
```

[n\_blocks] map of connections [block\_p, conn\_idx] per block

## 4.2 Engine\_methods

### Functions

- virtual int `engine_base::run` (value\_t n\_days)  
*runs simulation for the number of days using internal time management*
- virtual int `engine_base::run_timestep` (value\_t deltat, value\_t time)  
*runs simulation for one timestep starting from particular time*
- virtual int `engine_base::run_single_newton_iteration` (value\_t deltat)  
*report for one newton iteration*
- virtual int `engine_base::solve_linear_equation` ()
- virtual int `engine_base::post_newtonloop` (value\_t deltat, value\_t time)
- virtual int `engine_base::report` ()  
*reports complete information about well regimes*
- virtual int `engine_base::print_stat` ()  
*print statistics for the current run*
- virtual int `engine_base::test_assembly` (int n\_times, int kernel\_number=0, int dump\_jacobian=0)
- virtual int `engine_base::test_spmv` (int n\_timer, int kernel\_number=0, int dump\_result=0)
- virtual int `engine_base_gpu::run_timestep` (value\_t deltat, value\_t time)  
*runs simulation for one timestep starting from particular time*
- virtual int `engine_base_gpu::test_assembly` (int n\_times, int kernel\_number=0, int dump\_jacobian\_rhs=0)
- virtual int `engine_base_gpu::test_spmv` (int n\_times, int kernel\_number=0, int dump\_result=0)

### Variables

- value\_t \* `engine_base_gpu::X_d`
- value\_t \* `engine_base_gpu::Xn_d`
- value\_t \* `engine_base_gpu::dX_d`
- value\_t \* `engine_base_gpu::RHS_d`
- value\_t \* `engine_base_gpu::RHS_wells_d`
- std::vector< value\_t > `engine_base_gpu::jac_wells`
- value\_t \* `engine_base_gpu::jac_wells_d`
- std::vector< index\_t > `engine_base_gpu::jac_well_head_idx`
- index\_t \* `engine_base_gpu::jac_well_head_idx_d`
- value\_t \* `engine_base_gpu::op_vals_arr_d`
- value\_t \* `engine_base_gpu::op_ders_arr_d`
- value\_t \* `engine_base_gpu::op_vals_arr_n_d`
- std::vector< index\_t \* > `engine_base_gpu::block_idx`
- value\_t \* `engine_base_gpu::RV_d`
- value\_t \* `engine_base_gpu::PV_d`
- value\_t \* `engine_base_gpu::mesh_tran_d`
- value\_t \* `engine_base_gpu::mesh_tranD_d`
- value\_t \* `engine_base_gpu::mesh_hcap_d`
- int `engine_base_gpu::min_grid_size`
- int `engine_base_gpu::grid_size`
- std::vector< int > `engine_base_gpu::assembly_block_sizes`

#### 4.2.1 Detailed Description

Methods of base engine class exposed to Python

## 4.2.2 Function Documentation

### 4.2.2.1 print\_stat()

```
int engine_base::print_stat ( ) [virtual]
```

print statistics for the current run

This procedure prints all statistics of simultion run

#### Note

The statistics includes the following items:

- total timesteps n\_timesteps\_total,
- wasted timesteps n\_timesteps\_wasted,
- total number of Neton iterations n\_newton\_total,
- number of wated Newton iterations n\_newton\_wasted,
- number of linear iterations n\_linear\_total,
- number of waterd linear iterations n\_linear\_wasted
- extended OBL statistics

### 4.2.2.2 report()

```
int engine_base::report ( ) [virtual]
```

reports complete information about well regimes

This method adds averaged and accumulated phase rates over the period since the last report call till current moment (possibly spannin over several timesteps) to time\_data\_report array.

### 4.2.2.3 run()

```
int engine_base::run (
    value_t n_days ) [virtual]
```

runs simulation for the number of days using internal time management

This base method runs simulation for particular time period. It use various parameters kept from the previous run in internal structures. The timestep managements is performed based on internal parameters (see 'params' class)

#### Parameters

<code>n_days</code>	- number of days for simulation
---------------------	---------------------------------

**Note**

this procedure involve several internal parameters including:

- mesh - mesh information for simulation
- params - all parameters for simulation
- wells - well input used in simulation
- Xn and X - solution for initial and following timesteps

**4.2.2.4 run\_timestep()** [1/2]

```
int engine_base_gpu::run_timestep (
    value_t deltat,
    value_t time ) [virtual]
```

runs simulation for one timestep starting from particular time

This base method runs simulation for a single timestep. For compatibility between different runs, optional value for a current timestep can be provided.

**Parameters**

<i>n_days</i>	- number of days for simulation
<i>time</i>	- starting time for the timestep

**Note**

this procedure involve several internal parameters including:

- mesh - mesh information for simulation
- params - all parameters for simulation
- wells - well input used in simulation
- Xn and X - solution for initial and following timesteps

Reimplemented from [engine\\_base](#).

**4.2.2.5 run\_timestep()** [2/2]

```
int engine_base::run_timestep (
    value_t deltat,
    value_t time ) [virtual]
```

runs simulation for one timestep starting from particular time

This base method runs simulation for a single timestep. For compatibility between different runs, optional value for a current timestep can be provided.

## Parameters

<i>n_days</i>	- number of days for simulation
<i>time</i>	- starting time for the timestep

## Note

this procedure involve several internal parameters including:

- mesh - mesh information for simulation
- params - all parameters for simulation
- wells - well input used in simulation
- Xn and X - solution for initial and following timesteps

Reimplemented in [engine\\_base\\_gpu](#).

## 4.3 Engine\_parameters

### Variables

- `std::vector< value_t > engine_base::X`  
*vector of unknowns in the current timestep*
- `std::vector< value_t > engine_base::Xn`  
*vector of unknowns in the previous timestep*
- `value_t engine_base::t`  
*current timestep*
- `conn_mesh * engine_base::mesh`  
*pointer to mesh*
- `sim_params * engine_base::params`  
*simulation parameters*
- `sim_stat engine_base::stat`  
*simulation statistics*
- `std::vector< ms_well * > engine_base::wells`  
*vector of wells*
- `std::unordered_map< std::string, std::vector< value_t > > engine_base::time_data`  
*unsorted map containing well information (BHP, rates)*

### 4.3.1 Detailed Description

Parameters in base engine class exposed to Python

## 4.4 Well\_controls

### Classes

- class [bhp\\_inj\\_well\\_control](#)  
*BHP control for injection compositional well.*
- class [bhp\\_prod\\_well\\_control](#)  
*BHP control for production compositional well.*
- class [rate\\_inj\\_well\\_control](#)  
*Volumetric rate control for injection compositional well.*
- class [rate\\_prod\\_well\\_control](#)  
*Volumetric rate control for production compositional well.*
- class [gt\\_bhp\\_temp\\_inj\\_well\\_control](#)  
*BHP and temperature control for injection geothermal well.*
- class [gt\\_bhp\\_prod\\_well\\_control](#)  
*BHP control for production geothermal well.*
- class [gt\\_rate\\_temp\\_inj\\_well\\_control](#)  
*Volumetric rate and temperature control for injection geothermal well.*
- class [gt\\_rate\\_prod\\_well\\_control](#)  
*Volumetric rate control for production geothermal well.*
- class [gt\\_mass\\_rate\\_enthalpy\\_inj\\_well\\_control](#)  
*Mass rate and enthalpy control for injection geothermal well.*
- class [gt\\_mass\\_rate\\_prod\\_well\\_control](#)  
*Mass rate control for production geothermal well.*

### 4.4.1 Detailed Description

Methods for well control/constraint exposed to Python



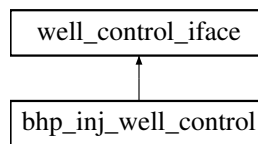
## Chapter 5

# Class Documentation

### 5.1 bhp\_inj\_well\_control Class Reference

BHP control for injection compositional well.

Inheritance diagram for bhp\_inj\_well\_control:



#### Public Member Functions

- **bhp\_inj\_well\_control** (value\_t target\_pressure\_, std::vector< value\_t > &injection\_stream\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **add\_to\_csr\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

#### Public Attributes

- value\_t **target\_pressure**
- std::vector< value\_t > **injection\_stream**

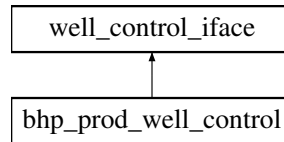
#### 5.1.1 Detailed Description

BHP control for injection compositional well.

## 5.2 bhp\_prod\_well\_control Class Reference

BHP control for production compositional well.

Inheritance diagram for bhp\_prod\_well\_control:



### Public Member Functions

- **bhp\_prod\_well\_control** (value\_t target\_pressure\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **add\_to\_csr\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

### Public Attributes

- value\_t **target\_pressure**

### 5.2.1 Detailed Description

BHP control for production compositional well.

## 5.3 block\_perf Struct Reference

Structure for well perforation.

### Public Member Functions

- [block\\_perf](#) ()  
*transmissibility between reservoir block and well block*

### Public Attributes

- index\_t **reservoir\_block**
- value\_t [well\\_index](#)  
*the block of reservoir which is perforated*

### 5.3.1 Detailed Description

Structure for well perforation.

## 5.4 block\_well Class Reference

Class for well definition (both segments and controls)

### Public Member Functions

- void **set\_nc** (int nc\_)

### Public Attributes

- std::vector< [block\\_perf](#) > **block\_perf\_list**
- std::vector< std::pair< int, [well\\_control](#) > > **control\_list**
- [well\\_control](#) **current\_control**  
*a list of well controls and correspondent report timestep*
- index\_t **first\_well\_block\_index**  
*effective well control to be used in jacobian assembly*
- index\_t **ghost\_well\_block\_index**  
*index of the first well block, which connects to ghost well block*
- index\_t **NC**  
*index of the first well block, which connects to ghost well block*
- value\_t **well\_block\_volume**
- value\_t **well\_block\_trans**  
*volume of well block*
- value\_t \* **current\_rates**  
*transmissibility bewteen well blocks*
- value\_t **current\_BHP**  
*current molar rates taken as influx/outflux of ghost block for production/injection well respectively*
- value\_t **current\_temp**  
*current BHP for well*
- [well\\_control\\_iface](#) \* **control**  
*current temperature for well*
- [well\\_control\\_iface](#) \* **constraint**  
*set of controls*
- std::string **name**  
*set of constraints*

### 5.4.1 Detailed Description

Class for well definition (both segments and controls)

## 5.5 conn\_mesh Class Reference

This class defines mesh and corresponding arrays.

### Public Member Functions

- `int init_poro (std::string poro_filename)`
- `int init_grav_coef (value_t grav_const=9.80665e-5)`
- `int save_keyword_compressed (std::string filename, std::string keyword, value_t *data, index_t length)`
- `int get_res_tran (std::vector< value_t > &res_tran, std::vector< value_t > &res_tranD)`
- `int set_res_tran (std::vector< value_t > &res_tran, std::vector< value_t > &res_tranD)`
- `int get_wells_tran (std::vector< value_t > &wells_tran)`
- `int set_wells_tran (std::vector< value_t > &wells_tran)`
- `int save_volume (std::string filename)`
- `int save_poro (std::string filename)`
- `int save_pressure (std::string filename)`
- `int save_zmf (std::string filename)`
- `int save_temperature (std::string filename)`
- `int save_enthalpy (std::string filename)`
- `int save_wells (std::string filename, std::vector< block_well > &well_list, sim_params &params)`
- `int init (std::string conn2p_filename)`  
*init mesh by reading TPFACONNS keyword file*
- `int init (std::vector< index_t > &block_m, std::vector< index_t > &block_p, std::vector< value_t > &tran, std::vector< value_t > &tranD)`  
*init mesh by reading array of left/right neighbours*
- `int init_mpfa (std::vector< index_t > &block_m, std::vector< index_t > &block_p, std::vector< index_t > &fstencil, std::vector< index_t > &fst_offset, std::vector< value_t > &franc, std::vector< value_t > &rhs, uint8_t _n_dim, index_t _n_matrix, index_t _n_bounds)`  
*init mesh by reading MPFA connections*
- `int init_mpsa (std::vector< index_t > &block_m, std::vector< index_t > &block_p, std::vector< index_t > &sstencil, std::vector< index_t > &sst_offset, std::vector< value_t > &stranc, uint8_t _n_dim, index_t _n_matrix, index_t _n_bounds, index_t _n_fracs)`  
*init mesh by reading MPSA connections*
- `int init_pm (std::vector< index_t > &block_m, std::vector< index_t > &block_p, std::vector< index_t > &stencil, std::vector< index_t > &st_offset, std::vector< value_t > &tran, std::vector< value_t > &rhs, index_t _n_matrix, index_t _n_bounds, index_t _n_fracs)`  
*init mesh by reading both MPFA and MPSA connections*
- `int init_pm (std::vector< index_t > &block_m, std::vector< index_t > &block_p, std::vector< index_t > &stencil, std::vector< index_t > &st_offset, std::vector< value_t > &tran, std::vector< value_t > &rhs, std::vector< value_t > &tran_biot, std::vector< value_t > &rhs_biot, index_t _n_matrix, index_t _n_bounds, index_t _n_fracs)`
- `int init_const_1d (double trans_const, index_t nb)`  
*init mesh for 1D reservoir with 'nb' blocks*
- `int add_conn (index_t block_m, index_t block_p, value_t trans)`  
*add a new connection to connection list*
- `int add_conn_mpfa (index_t block_m, index_t block_p, value_t trans)`
- `int reverse_and_sort ()`  
*reverse connections and sort them by both row and col*
- `int reverse_and_sort_dvel ()`  
*reverse connections and renumerate velocity mappers and sort them by both row and col*
- `int reverse_and_sort_mpfa ()`  
*reverse mpsa connections and sort them by both row and col*

- int [reverse\\_and\\_sort\\_mpsa](#) ()
- int [reverse\\_and\\_sort\\_pm](#) ()
- int [add\\_wells](#) (std::vector< [ms\\_well](#) \*> &wells)  
*discretize ms wells into reservoir*
- int [add\\_wells\\_mpfa](#) (std::vector< [ms\\_well](#) \*> &wells)

## Public Attributes

- index\_t [n\\_res\\_blocks](#)
- index\_t [n\\_res\\_well\\_blocks](#)
- index\_t [n\\_blocks](#)
- index\_t [n\\_conns](#)
- index\_t [n\\_perfs](#)
- index\_t [n\\_matrix](#)
- index\_t [n\\_bounds](#) = 0
- index\_t [n\\_fracs](#) = 0
- std::vector< index\_t > [one\\_way\\_to\\_conn\\_index\\_forward](#)
- std::vector< index\_t > [one\\_way\\_to\\_conn\\_index\\_reverse](#)
- std::vector< index\_t > [conn\\_index\\_to\\_one\\_way](#)
- std::vector< index\_t > [block\\_m](#)  
*[n\_conns] array of indices of blocks on the minus side of a connection (smaller index)*
- std::vector< index\_t > [block\\_p](#)  
*[n\_conns] array of indices of blocks on the plus side of a connection (bigger index)*
- std::vector< value\_t > [tran](#)  
*[n\_conns] array of transmissibility values for given connection*
- std::vector< value\_t > [tranD](#)  
*[n\_conns] array of diffusion transmissibility values for given connection (transmis value)*
- std::vector< value\_t > [grav\\_coef](#)  
*[n\_conns] array of gravity coefficient for every connection ( = (depth[block\_m] - depth[block\_p]) \* g)*
- std::vector< value\_t > [velocity](#)  
*[n\_conns] array of initial velocity values (Decouple - velocity engine)*
- std::vector< value\_t > [tran\\_const](#)  
*[n\_conns] array of temporary const transmissibilities*
- uint8\_t [n\\_vars](#)  
*Number of unknowns per block.*
- std::vector< index\_t > [fstencil](#)  
*array of indices of blocks are neccessary for each connection*
- std::vector< index\_t > [fst\\_offset](#)  
*[n\_conns + 1] array of offsets of the first block of connection in 'stencil'*
- std::vector< index\_t > [sstencil](#)  
*array of indices of blocks are neccessary for each connection*
- std::vector< index\_t > [sst\\_offset](#)  
*[n\_conns + 1] array of offsets of the first block of connection in 'stencil'*
- std::vector< value\_t > [stran](#)  
*[n\_conns] array of transmissibility values for given connection*
- std::vector< value\_t > [stran\\_biot](#)  
*[n\_conns] array of transmissibility values for biot contribution to the given connection*
- std::vector< std::vector< int > > [stencil](#)
- std::vector< value\_t > [rhs](#)
- std::vector< value\_t > [rhs\\_biot](#)
- std::vector< value\_t > [f](#)

- `index_t n_links`  
*number of non-zero links*
- `std::vector< value_t > volume`  
*[n\_blocks] array of volumes of mesh blocks*
- `std::vector< value_t > poro`  
*[n\_blocks] array of porosities of mesh blocks*
- `std::vector< value_t > depth`  
*[n\_blocks] array of depths*
- `std::vector< value_t > heat_capacity`  
*[n\_blocks] array of heat capacity of rock*
- `std::vector< value_t > rock_cond`  
*[n\_blocks] array of heat conduction of rock;*
- `std::vector< value_t > kin_factor`  
*[n\_blocks] array of kinetic rate constants (dependent on the initial porosity and other factors!);*
- `std::vector< value_t > pressure`  
*[n\_blocks] array of initial pressure values*
- `std::vector< value_t > composition`  
*[n\_blocks] array of initial composition values*
- `std::vector< value_t > temperature`  
*[n\_blocks] array of initial temperature values*
- `std::vector< value_t > enthalpy`  
*[n\_blocks] array of initial enthalpy values*
- `std::vector< value_t > displacement`  
*[n\_dim \* n\_blocks] array of initial displacements values*
- `std::vector< value_t > bc`  
*[(1 + n\_dim) \* n\_bounds] array of boundary conditions*
- `std::vector< value_t > bc_prev`  
*[(1 + n\_dim) \* n\_bounds] array of boundary conditions*
- `std::vector< value_t > pz_bounds`  
*[nc \* n\_bounds] array of pressures and (inflow) fractions at boundaries*
- `std::vector< value_t > biot`  
*[9 \* n\_blocks] array of biot coefficients of mesh blocks*
- `std::vector< value_t > drained_compressibility`  
*[n\_blocks] array of drained compressibility of mesh blocks*
- `std::vector< index_t > op_num`  
*[n\_blocks] array of operator set index for every block*

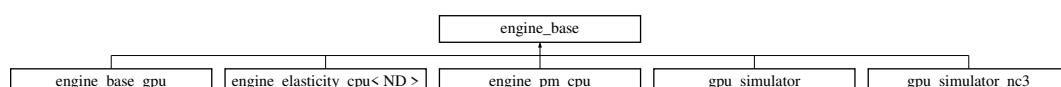
### 5.5.1 Detailed Description

This class defines mesh and corresponding arrays.

## 5.6 engine\_base Class Reference

This class defines infrastructure for simulation.

Inheritance diagram for engine\_base:



## Public Member Functions

- virtual const uint8\_t **get\_n\_vars** ()=0
- virtual const uint8\_t **get\_n\_ops** ()=0
- virtual const uint8\_t **get\_n\_comps** ()=0
- virtual const uint8\_t **get\_n\_fl\_var** ()
- virtual const uint8\_t **get\_z\_var** ()=0
- virtual int **init** ([conn\\_mesh](#) \*mesh\_, std::vector< [ms\\_well](#) \*> &well\_list\_, std::vector< operator\_set\_↵  
gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, [sim\\_params](#) \*params, timer\_node \*timer\_)=0
- template<uint8\_t N\_VARS>  
int **init\_base** ([conn\\_mesh](#) \*mesh\_, std::vector< [ms\\_well](#) \*> &well\_list\_, std::vector< operator\_set\_↵  
gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, [sim\\_params](#) \*params, timer\_node \*timer\_)
- virtual int **init\_jacobian\_structure** (csr\_matrix\_base \*jacobian)
- virtual int **assemble\_jacobian\_array** (value\_t dt, std::vector< value\_t > &X, csr\_matrix\_base \*jacobian,  
std::vector< value\_t > &RHS, int assemble\_kernel=0)=0
- virtual double **calc\_newton\_residual** ()
- virtual double **calc\_newton\_residual\_L1** ()
- virtual double **calc\_newton\_residual\_L2** ()
- virtual double **calc\_newton\_residual\_Linf** ()
- virtual double **calc\_well\_residual** ()
- virtual double **calc\_well\_residual\_L1** ()
- virtual double **calc\_well\_residual\_L2** ()
- virtual double **calc\_well\_residual\_Linf** ()
- virtual void **average\_operator** (std::vector< value\_t > &av\_op)
- virtual void **apply\_composition\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_global\_chop\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- virtual void **apply\_local\_chop\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_composition\_correction\_with\_solid** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_local\_chop\_correction\_with\_solid** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_composition\_correction\_new** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_global\_chop\_correction\_new** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_local\_chop\_correction\_new** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- virtual int **apply\_newton\_update** (value\_t dt)
- virtual void **apply\_obl\_axis\_local\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- double **evaluate\_next\_dt** ()
- virtual int **print\_timestep** (value\_t time, value\_t deltat)
- int **print\_header** ()
- virtual int **run** (value\_t n\_days)  
*runs simulation for the number of days using internal time management*
- virtual int **run\_timestep** (value\_t deltat, value\_t time)  
*runs simulation for one timestep starting from particular time*
- virtual int **run\_single\_newton\_iteration** (value\_t deltat)  
*report for one newton iteration*
- virtual int **solve\_linear\_equation** ()
- virtual int **post\_newtonloop** (value\_t deltat, value\_t time)
- virtual int **report** ()  
*reports complete information about well regimes*
- virtual int **print\_stat** ()  
*print statistics for the current run*
- virtual int **test\_assembly** (int n\_times, int kernel\_number=0, int dump\_jacobian=0)
- virtual int **test\_spmv** (int n\_timer, int kernel\_number=0, int dump\_result=0)

## Public Attributes

- `std::vector< value_t > X`  
*vector of unknowns in the current timestep*
- `std::vector< value_t > Xn`  
*vector of unknowns in the previous timestep*
- `value_t t`  
*current timestep*
- `conn_mesh * mesh`  
*pointer to mesh*
- `sim_params * params`  
*simulation parameters*
- `sim_stat stat`  
*simulation statistics*
- `std::vector< ms_well * > wells`  
*vector of wells*
- `std::unordered_map< std::string, std::vector< value_t > > time_data`  
*unsorted map containing well information (BHP, rates)*
- `linsolv_iface * linear_solver`
- `std::vector< operator_set_gradient_evaluator_iface * > acc_flux_op_set_list`
- `uint8_t n_vars`
- `uint8_t n_ops`
- `uint8_t nc`
- `uint8_t z_var`
- `double min_zc`
- `double max_zc`
- `std::vector< value_t > old_z`
- `std::vector< value_t > new_z`
- `uint8_t nc_fl`
- `std::vector< value_t > old_z_fl`
- `std::vector< value_t > new_z_fl`
- `std::vector< value_t > X_init`
- `std::vector< value_t > PV`
- `std::vector< value_t > RV`
- `std::vector< std::vector< index_t > > block_idx`
- `std::vector< std::vector< value_t > > op_axis_min`
- `std::vector< std::vector< value_t > > op_axis_max`
- `std::vector< value_t > op_vals_arr`
- `std::vector< value_t > op_ders_arr`
- `std::vector< value_t > op_vals_arr_n`
- `std::unordered_map< std::string, std::vector< value_t > > time_data_report`
- `std::vector< value_t > FIPS`
- `csr_matrix_base * Jacobian`
- `std::vector< value_t > X0`
- `std::vector< value_t > RHS`
- `std::vector< value_t > dX`
- `value_t dt`
- `value_t prev_usual_dt`
- `value_t stop_time`
- `value_t CFL_max`
- `index_t n_newton_last_dt`
- `index_t n_linear_last_dt`
- `double newton_residual_last_dt`

- double **well\_residual\_last\_dt**
- int **linear\_solver\_error\_last\_dt**
- timer\_node \* **timer**
- timer\_node **full\_step\_timer**
- double **full\_step\_run\_timer**
- double **t\_full\_step**

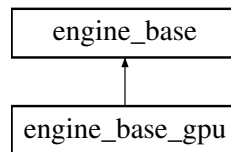
### 5.6.1 Detailed Description

This class defines infrastructure for simulation.

## 5.7 engine\_base\_gpu Class Reference

This class defines infrastructure for simulation.

Inheritance diagram for engine\_base\_gpu:



### Public Member Functions

- virtual uint8\_t const **get\_n\_vars** ()=0
- virtual uint8\_t const **get\_n\_ops** ()=0
- virtual uint8\_t const **get\_n\_comps** ()=0
- virtual uint8\_t const **get\_z\_var** ()=0
- virtual int **init** (conn\_mesh \*mesh\_, std::vector< ms\_well \*> &well\_list\_, std::vector< operator\_set\_↔ gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, sim\_params \*params, timer\_node \*timer\_)=0
- template<uint8\_t N\_VARS>  
int **init\_base** (conn\_mesh \*mesh\_, std::vector< ms\_well \*> &well\_list\_, std::vector< operator\_set\_↔ gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, sim\_params \*params, timer\_node \*timer\_)
- virtual int **assemble\_jacobian\_array** (value\_t dt, std::vector< value\_t > &X, csr\_matrix\_base \*jacobian, std::vector< value\_t > &RHS, int assemble\_kernel=0)=0
- void **apply\_composition\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_global\_chop\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **apply\_local\_chop\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- int **apply\_newton\_update** (value\_t dt)
- virtual int **run\_timestep** (value\_t deltat, value\_t time)  
*runs simulation for one timestep starting from particular time*
- virtual int **test\_assembly** (int n\_times, int kernel\_number=0, int dump\_jacobian\_rhs=0)
- virtual int **test\_spmv** (int n\_times, int kernel\_number=0, int dump\_result=0)

## Public Attributes

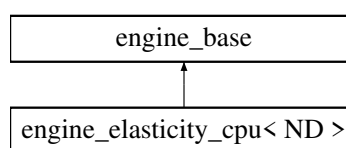
- value\_t \* **X\_d**
- value\_t \* **Xn\_d**
- value\_t \* **dX\_d**
- value\_t \* **RHS\_d**
- value\_t \* **RHS\_wells\_d**
- std::vector< value\_t > **jac\_wells**
- value\_t \* **jac\_wells\_d**
- std::vector< index\_t > **jac\_well\_head\_idx**
- index\_t \* **jac\_well\_head\_idx\_d**
- value\_t \* **op\_vals\_arr\_d**
- value\_t \* **op\_ders\_arr\_d**
- value\_t \* **op\_vals\_arr\_n\_d**
- std::vector< index\_t \* > **block\_idx**
- value\_t \* **RV\_d**
- value\_t \* **PV\_d**
- value\_t \* **mesh\_tran\_d**
- value\_t \* **mesh\_tranD\_d**
- value\_t \* **mesh\_hcap\_d**
- int **min\_grid\_size**
- int **grid\_size**
- std::vector< int > **assembly\_block\_sizes**

### 5.7.1 Detailed Description

This class defines infrastructure for simulation.

## 5.8 engine\_elasticity\_cpu< ND > Class Template Reference

Inheritance diagram for engine\_elasticity\_cpu< ND >:



## Public Member Functions

- const uint8\_t **get\_n\_vars** () override
- const uint8\_t **get\_n\_ops** ()
- const uint8\_t **get\_n\_dim** ()
- const uint8\_t **get\_n\_comps** ()
- const uint8\_t **get\_z\_var** ()
- int **init** (**conn\_mesh** \*mesh\_, std::vector< **ms\_well** \*> &well\_list\_, std::vector< operator\_set\_gradient\_↵ evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, **sim\_params** \*params\_, timer\_node \*timer\_)
- int **init\_base** (**conn\_mesh** \*mesh\_, std::vector< **ms\_well** \*> &well\_list\_, std::vector< operator\_set\_↵ gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, **sim\_params** \*params\_, timer\_node \*timer\_)
- int **init\_jacobian\_structure\_mpsa** (csr\_matrix\_base \*jacobian)
- int **assemble\_jacobian\_array** (value\_t dt, std::vector< value\_t > &**X**, csr\_matrix\_base \*jacobian, std↵::vector< value\_t > &RHS, int assemble\_kernel=0)

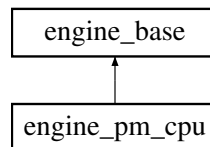
### Static Public Attributes

- static const uint8\_t **ND\_** = ND
- static const uint8\_t **N\_VARS** = ND
- static const uint8\_t **U\_VAR** = 0
- static const uint8\_t **N\_OPS** = ND\_
- static const uint8\_t **ACC\_OP** = 0
- static const uint8\_t **FLUX\_OP** = 0
- static const uint8\_t **N\_VARS\_SQ** = N\_VARS \* N\_VARS

### Additional Inherited Members

## 5.9 engine\_pm\_cpu Class Reference

Inheritance diagram for engine\_pm\_cpu:



### Public Member Functions

- const uint8\_t **get\_n\_vars** () override
- const uint8\_t **get\_n\_ops** ()
- const uint8\_t **get\_n\_dim** ()
- const uint8\_t **get\_n\_comps** ()
- const uint8\_t **get\_z\_var** ()
- int **init** (conn\_mesh \*mesh\_, std::vector< ms\_well \*> &well\_list\_, std::vector< operator\_set\_gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, sim\_params \*params\_, timer\_node \*timer\_)
- int **init\_base** (conn\_mesh \*mesh\_, std::vector< ms\_well \*> &well\_list\_, std::vector< operator\_set\_gradient\_evaluator\_iface \*> &acc\_flux\_op\_set\_list\_, sim\_params \*params\_, timer\_node \*timer\_)
- int **init\_jacobian\_structure\_pm** (csr\_matrix\_base \*jacobian)
- int **assemble\_jacobian\_array** (value\_t dt, std::vector< value\_t > &X, csr\_matrix\_base \*jacobian, std::vector< value\_t > &RHS, int assemble\_kernel=0)
- int **solve\_linear\_equation** ()
- void **apply\_obl\_axis\_local\_correction** (std::vector< value\_t > &X, std::vector< value\_t > &dX)
- void **extract\_Xop** ()
- std::vector< value\_t > **calc\_newton\_dev\_L2** ()
- std::vector< value\_t > **calc\_newton\_dev** ()

### Public Attributes

- std::vector< value\_t > **Xop**  
*vector of unknowns in the current timestep provided for operator evaluation*
- value\_t **deviation\_u**
- value\_t **deviation\_p**

### Static Public Attributes

- static const uint8\_t **ND\_** = 3
- static const uint8\_t **NC\_** = 1
- static const uint8\_t **NT\_** = 4
- static const uint8\_t **N\_VARS** = NC\_ + ND\_
- static const uint8\_t **U\_VAR** = 0
- static const uint8\_t **P\_VAR** = 3
- static const uint8\_t **Z\_VAR** = 255
- static const uint8\_t **N\_OPS** = 2 \* NC\_
- static const uint8\_t **ACC\_OP** = 0
- static const uint8\_t **FLUX\_OP** = NC\_
- static const uint8\_t **GRAV\_OP** = 0
- static const uint8\_t **N\_VARS\_SQ** = N\_VARS \* N\_VARS

## 5.10 pm::Face Class Reference

### Public Member Functions

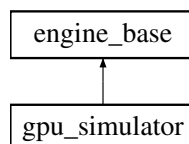
- **Face** (index\_t \_type, index\_t \_cell\_id1, index\_t \_cell\_id2, index\_t \_face\_id1, index\_t \_face\_id2, value\_t \_↔ area, std::valarray< value\_t > &\_n, std::valarray< value\_t > &\_c)

### Public Attributes

- index\_t **type**
- index\_t **cell\_id1**
- index\_t **cell\_id2**
- index\_t **face\_id1**
- index\_t **face\_id2**
- [Matrix](#) **n**
- [Matrix](#) **c**
- value\_t **area**

## 5.11 gpu\_simulator Class Reference

Inheritance diagram for gpu\_simulator:



### Public Member Functions

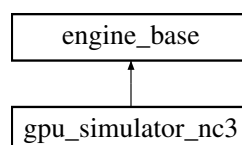
- int **init** ([conn\\_mesh](#) \*\_mesh, std::string table\_base\_name)
- int **run** ([sim\\_params](#) \*params)
- int **assemble\_jacobian** (value\_t dt, int is\_first)
- int **gpu\_test** (int argc, char \*\*argv)

## Public Attributes

- [conn\\_mesh](#) \* **mesh**
- [sim\\_params](#) **params**
- linear\_solver\_base \* **cpu\_solver**
- linear\_solver\_base \* **cpu\_preconditioner**
- LinearSolver \* **gpu\_solver**
- Preconditioner \* **gpu\_preconditioner**
- interp\_table \* **acc1**
- interp\_table \* **acc2**
- interp\_table \* **flu1**
- interp\_table \* **flu2**
- csr\_matrix **Jacobian**
- std::vector< value\_t > **RHS**
- std::vector< value\_t > **X**
- std::vector< value\_t > **Xn**
- std::vector< value\_t > **dX**
- float **gpu\_assemble\_timer**
- value\_t \* **gpu\_acc1\_data**
- interp\_value\_t \* **gpu\_acc1\_res**
- value\_t \* **gpu\_acc2\_data**
- interp\_value\_t \* **gpu\_acc2\_res**
- value\_t \* **gpu\_flu1\_data**
- interp\_value\_t \* **gpu\_flu1\_res**
- value\_t \* **gpu\_flu2\_data**
- interp\_value\_t \* **gpu\_flu2\_res**
- index\_t \* **gpu\_block\_m**
- index\_t \* **gpu\_block\_p**
- value\_t \* **gpu\_tran**
- value\_t \* **gpu\_PV**
- value\_t \* **gpu\_jac\_values**
- index\_t \* **gpu\_jac\_rows\_ptr**
- index\_t \* **gpu\_jac\_cols\_ind**
- value\_t \* **gpu\_jac\_values\_ilu**
- value\_t \* **gpu\_rhs**
- value\_t \* **gpu\_x**
- value\_t \* **gpu\_xn**
- value\_t \* **gpu\_dx**

## 5.12 gpu\_simulator\_nc3 Class Reference

Inheritance diagram for gpu\_simulator\_nc3:



## Public Member Functions

- int **init** ([conn\\_mesh](#) \* \_mesh, std::string table\_base\_name)
- int **run** ([sim\\_params](#) \*params)
- int **assemble\_jacobian** (value\_t dt, int is\_first)
- int **gpu\_test** (int argc, char \*\*argv)

## Public Attributes

- [conn\\_mesh](#) \* **mesh**
- [sim\\_params](#) **params**
- linear\_solver\_base \* **cpu\_solver**
- linear\_solver\_base \* **cpu\_preconditioner**
- LinearSolver \* **gpu\_solver**
- Preconditioner \* **gpu\_preconditioner**
- interp\_table\_3d \* **acc1**
- interp\_table\_3d \* **acc2**
- interp\_table\_3d \* **flu1**
- interp\_table\_3d \* **flu2**
- interp\_table\_3d \* **acc3**
- interp\_table\_3d \* **flu3**
- csr\_matrix **Jacobian**
- std::vector< value\_t > **RHS**
- std::vector< value\_t > **X**
- std::vector< value\_t > **Xn**
- std::vector< value\_t > **dX**
- double **interpolation\_timer**
- value\_t \* **gpu\_acc1\_data**
- interp\_value\_t \* **gpu\_acc1\_res**
- value\_t \* **gpu\_acc2\_data**
- interp\_value\_t \* **gpu\_acc2\_res**
- value\_t \* **gpu\_acc3\_data**
- interp\_value\_t \* **gpu\_acc3\_res**
- interp\_value\_t \* **gpu\_acc\_n\_res**
- value\_t \* **gpu\_flu1\_data**
- interp\_value\_t \* **gpu\_flu1\_res**
- value\_t \* **gpu\_flu2\_data**
- interp\_value\_t \* **gpu\_flu2\_res**
- value\_t \* **gpu\_flu3\_data**
- interp\_value\_t \* **gpu\_flu3\_res**
- index\_t \* **gpu\_block\_m**
- index\_t \* **gpu\_block\_p**
- value\_t \* **gpu\_tran**
- value\_t \* **gpu\_PV**
- value\_t \* **gpu\_jac\_values**
- index\_t \* **gpu\_jac\_rows\_ptr**
- index\_t \* **gpu\_jac\_cols\_ind**
- value\_t \* **gpu\_jac\_values\_ilu**
- value\_t \* **gpu\_rhs**
- value\_t \* **gpu\_x**
- value\_t \* **gpu\_xn**
- value\_t \* **gpu\_dx**
- float \* **gpu\_update\_ratio**

## 5.13 pm::pm\_discretizer::Gradients Struct Reference

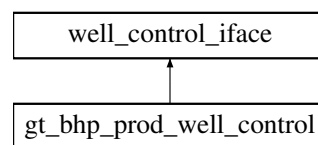
### Public Attributes

- `std::vector< index_t >` **stencil**
- [Matrix](#) **mat**
- [Matrix](#) **rhs**

## 5.14 gt\_bhp\_prod\_well\_control Class Reference

BHP control for production geothermal well.

Inheritance diagram for `gt_bhp_prod_well_control`:



### Public Member Functions

- **gt\_bhp\_prod\_well\_control** (`value_t target_pressure_`)
- virtual int **add\_to\_jacobian** (`value_t dt, index_t well_head_idx, value_t segment_trans, index_t n_block_size, std::vector< value_t > &X, value_t *jacobian_row, std::vector< value_t > &RHS`)
- virtual int **check\_constraint\_violation** (`value_t dt, index_t well_head_idx, value_t segment_trans, index_t n_block_size, std::vector< value_t > &X`)
- virtual int **initialize\_well\_block** (`std::vector< value_t > &state_block, const std::vector< value_t > &state_↔_neighbour`)

### Public Attributes

- `value_t` **target\_pressure**

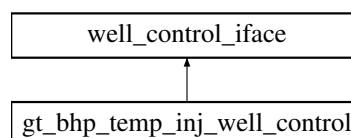
### 5.14.1 Detailed Description

BHP control for production geothermal well.

## 5.15 gt\_bhp\_temp\_inj\_well\_control Class Reference

BHP and temperature control for injection geothermal well.

Inheritance diagram for `gt_bhp_temp_inj_well_control`:



## Public Member Functions

- **gt\_bhp\_temp\_inj\_well\_control** (std::vector< std::string > phase\_names\_, index\_t n\_vars\_, value\_t target\_pressure\_, value\_t target\_temperature\_, std::vector< value\_t > injection\_stream\_, operator\_set\_gradient\_evaluator\_iface \*rate\_etor\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

## Public Attributes

- std::vector< std::string > **phase\_names**
- index\_t **n\_vars**
- index\_t **n\_phases**
- value\_t **target\_pressure**
- value\_t **target\_temperature**
- std::vector< value\_t > **injection\_stream**
- std::vector< value\_t > **state**
- std::vector< value\_t > **rate\_temp\_ops**
- std::vector< value\_t > **rate\_temp\_ops\_derivs**
- operator\_set\_gradient\_evaluator\_iface \* **rate\_etor**

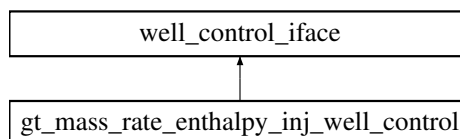
### 5.15.1 Detailed Description

BHP and temperature control for injection geothermal well.

## 5.16 gt\_mass\_rate\_enthalpy\_inj\_well\_control Class Reference

Mass rate and enthalpy control for injection geothermal well.

Inheritance diagram for gt\_mass\_rate\_enthalpy\_inj\_well\_control:



## Public Member Functions

- **gt\_mass\_rate\_enthalpy\_inj\_well\_control** (std::vector< std::string > phase\_names\_, index\_t target\_phase\_idx\_, index\_t n\_variables\_, std::vector< value\_t > injection\_stream\_, value\_t target\_rate\_, value\_t target\_enthalpy\_, operator\_set\_gradient\_evaluator\_iface \*rate\_etor\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

## Public Attributes

- `std::vector< std::string > phase_names`
- `std::vector< value_t > state`
- `std::vector< value_t > injection_stream`
- `std::vector< value_t > rate_temp_ops`
- `std::vector< value_t > rate_temp_ops_derivs`
- `index_t target_phase_idx`
- `index_t n_variables`
- `index_t n_phases`
- `value_t target_rate`
- `value_t target_enthalpy`
- `operator_set_gradient_evaluator_iface * rate_etor`

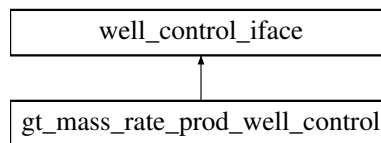
## 5.16.1 Detailed Description

Mass rate and enthalpy control for injection geothermal well.

## 5.17 gt\_mass\_rate\_prod\_well\_control Class Reference

Mass rate control for production geothermal well.

Inheritance diagram for `gt_mass_rate_prod_well_control`:



## Public Member Functions

- **`gt_mass_rate_prod_well_control`** (`std::vector< std::string > phase_names_`, `index_t target_phase_idx_`, `index_t n_variables_`, `value_t target_rate_`, `operator_set_gradient_evaluator_iface *rate_etor_`)
- virtual int **`add_to_jacobian`** (`value_t dt`, `index_t well_head_idx`, `value_t segment_trans`, `index_t n_block_size`, `std::vector< value_t > &X`, `value_t *jacobian_row`, `std::vector< value_t > &RHS`)
- virtual int **`check_constraint_violation`** (`value_t dt`, `index_t well_head_idx`, `value_t segment_trans`, `index_t n_block_size`, `std::vector< value_t > &X`)
- virtual int **`initialize_well_block`** (`std::vector< value_t > &state_block`, `const std::vector< value_t > &state_neighbour`)

## Public Attributes

- `std::vector< std::string > phase_names`
- `std::vector< value_t > state`
- `std::vector< value_t > rate_temp_ops`
- `std::vector< value_t > rate_temp_ops_derivs`
- `index_t target_phase_idx`
- `index_t n_variables`
- `index_t n_phases`
- `value_t target_rate`
- `operator_set_gradient_evaluator_iface * rate_etor`

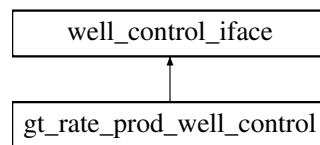
### 5.17.1 Detailed Description

Mass rate control for production geothermal well.

## 5.18 gt\_rate\_prod\_well\_control Class Reference

Volumetric rate control for production geothermal well.

Inheritance diagram for gt\_rate\_prod\_well\_control:



### Public Member Functions

- **gt\_rate\_prod\_well\_control** (std::vector< std::string > phase\_names\_, index\_t target\_phase\_idx\_, index\_t n\_vars, value\_t target\_rate\_, operator\_set\_gradient\_evaluator\_iface \*rate\_etc\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

### Public Attributes

- std::vector< std::string > **phase\_names**
- std::vector< value\_t > **state**
- std::vector< value\_t > **rate\_temp\_ops**
- std::vector< value\_t > **rate\_temp\_ops\_derivs**
- index\_t **target\_phase\_idx**
- index\_t **n\_variables**
- index\_t **n\_phases**
- value\_t **target\_rate**
- operator\_set\_gradient\_evaluator\_iface \* **rate\_etc**

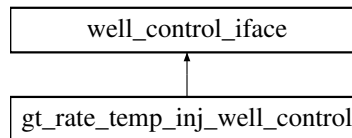
### 5.18.1 Detailed Description

Volumetric rate control for production geothermal well.

## 5.19 gt\_rate\_temp\_inj\_well\_control Class Reference

Volumetric rate and temperature control for injection geothermal well.

Inheritance diagram for gt\_rate\_temp\_inj\_well\_control:



### Public Member Functions

- **gt\_rate\_temp\_inj\_well\_control** (std::vector< std::string > phase\_names\_, index\_t target\_phase\_idx\_, index\_t n\_variables\_, value\_t target\_rate\_, value\_t target\_temp\_, std::vector< value\_t > &injection\_stream\_, operator\_set\_gradient\_evaluator\_iface \*rate\_etor\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

### Public Attributes

- std::vector< std::string > **phase\_names**
- index\_t **target\_phase\_idx**
- index\_t **n\_equations**
- index\_t **n\_variables**
- size\_t **n\_phases**
- value\_t **target\_rate**
- value\_t **target\_temperature**
- std::vector< value\_t > **injection\_stream**
- std::vector< value\_t > **state**
- std::vector< value\_t > **rate\_temp\_ops**
- std::vector< value\_t > **rate\_temp\_ops\_derivs**
- operator\_set\_gradient\_evaluator\_iface \* **rate\_etor**

#### 5.19.1 Detailed Description

Volumetric rate and temperature control for injection geothermal well.

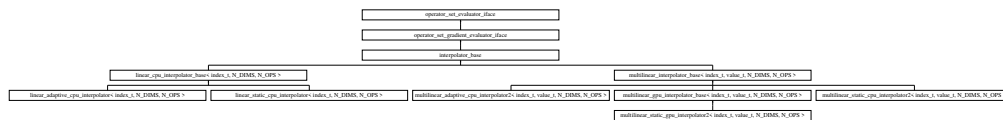
## 5.20 pm::pm\_discretizer::InnerMatrices Struct Reference

### Public Attributes

- [Matrix A1](#)
- [Matrix A2](#)
- [Matrix Q1](#)
- [Matrix Q2](#)
- [Matrix Th1](#)
- [Matrix Th2](#)
- [Matrix R1](#)
- [Matrix R2](#)
- [Matrix y1](#)
- [Matrix y2](#)
- [value\\_t r1](#)
- [value\\_t r2](#)

## 5.21 interpolator\_base Class Reference

Inheritance diagram for interpolator\_base:



### Public Member Functions

- [interpolator\\_base](#) ([operator\\_set\\_evaluator\\_iface](#) \*[supporting\\_point\\_evaluator](#), const std::vector< int > &[axes\\_points](#), const std::vector< double > &[axes\\_min](#), const std::vector< double > &[axes\\_max](#))  
Construct an interpolator with predefined parametrization space.
- virtual int [init](#) ()  
Initialize interpolator, perform internal sanity checks unavailable at construction time.
- int [evaluate](#) (const std::vector< double > &state, std::vector< double > &values)  
Evaluate all operators at the given state (point in parametrization space) Runs timer and calls virtual interpolate routine.
- int [evaluate\\_with\\_derivatives](#) (const std::vector< double > &states, const std::vector< int > &states\_idx, std::vector< double > &values, std::vector< double > &derivatives)  
Evaluate operators and their gradient for every specified state (point in parametrization space)
- virtual int [interpolate](#) (const std::vector< double > &point, std::vector< double > &values)=0  
Compute interpolation for all operators at the given point.
- virtual int [interpolate\\_with\\_derivatives](#) (const std::vector< double > &points, const std::vector< int > &points\_idx, std::vector< double > &values, std::vector< double > &derivatives)=0  
Compute interpolation and its gradient for all operators at every specified point.
- virtual int [get\\_n\\_dims](#) ()=0  
Get the number of dimensions in interpolation space Virtual, to be overridden by a child class.
- virtual int [get\\_n\\_ops](#) ()=0  
Get the number of operators Virtual, to be overridden by a child class.
- int [get\\_axis\\_n\\_points](#) (int axis)

- Get the number of supporting points for the given axis.*
- double [get\\_axis\\_min](#) (int axis)  
*Get the parametrization minimum value for given axis.*
- double [get\\_axis\\_max](#) (int axis)  
*Get the parametrization maximum value for given axis.*
- uint64\_t [get\\_n\\_interpolations](#) ()  
*Get the number of interpolations that took place.*
- uint64\_t [get\\_n\\_points\\_total](#) ()  
*Get the total number of supporting points in parameter space.*
- uint64\_t [get\\_n\\_points\\_used](#) ()  
*Get the number of supporting points used (evaluated through supporting\_point\_evaluator) The number is equal to n\_points\_total for static interpolation methods.*

### Protected Attributes

- const std::vector< int > [axes\\_points](#)  
*number of supporting points along each axis*
- const std::vector< double > [axes\\_min](#)  
*minimum at each axis*
- const std::vector< double > [axes\\_max](#)  
*maximum of each axis*
- operator\_set\_evaluator\_iface \* [supporting\\_point\\_evaluator](#)  
*object which computes operator values for supporting points*
- std::vector< double > [axes\\_step](#)  
*the distance between neighbor supporting points for each axis*
- std::vector< double > [axes\\_step\\_inv](#)  
*inverse of step (to avoid division)*
- uint64\_t [n\\_interpolations](#)  
*Number of interpolations that took place.*
- uint64\_t [n\\_points\\_total](#)  
*Total number of parametrization points.*
- double [n\\_points\\_total\\_fp](#)  
*Total number of parametrization points in floating point format, to detect index overflow in derived classes.*
- uint64\_t [n\\_points\\_used](#)  
*Number of parametrization points which were used (equal to n\_points\_total for static interpolators)*
- std::vector< double > [new\\_point\\_coords](#)  
*intermediate storage for supporting point generation*
- std::vector< double > [new\\_operator\\_values](#)  
*intermediate storage for supporting point generation*

#### 5.21.1 Detailed Description

Interpolator base class

#### 5.21.2 Constructor & Destructor Documentation

### 5.21.2.1 interpolator\_base()

```

interpolator_base::interpolator_base (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )

```

Construct an interpolator with predefined parametrization space.

#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operator values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

## 5.21.3 Member Function Documentation

### 5.21.3.1 evaluate()

```

int interpolator_base::evaluate (
    const std::vector< double > & state,
    std::vector< double > & values )

```

Evaluate all operators at the given state (point in parametrization space) Runs timer and calls virtual interpolate routine.

#### Parameters

in	<i>state</i>	Coordinates in parametrization space
out	<i>values</i>	Interpolated values

#### Returns

0 if evaluation is successful

### 5.21.3.2 evaluate\_with\_derivatives()

```

int interpolator_base::evaluate_with_derivatives (
    const std::vector< double > & states,
    const std::vector< int > & states_idx,
    std::vector< double > & values,
    std::vector< double > & derivatives )

```

Evaluate operators and their gradient for every specified state (point in parametrization space)

## Parameters

in	<i>states</i>	Array of coordinates in parametrization space
in	<i>states_idx</i>	Indexes of states in the input array which are marked for evaluation
out	<i>values</i>	Interpolated values
out	<i>derivatives</i>	Interpolation gradients

## Returns

0 if evaluation is successful

## 5.21.3.3 get\_axis\_max()

```
value_t interpolator_base::get_axis_max (
    int axis )
```

Get the parametrization maximum value for given axis.

## Parameters

<i>axis</i>	index of axis in question
-------------	---------------------------

## 5.21.3.4 get\_axis\_min()

```
value_t interpolator_base::get_axis_min (
    int axis )
```

Get the parametrization minimum value for given axis.

## Parameters

<i>axis</i>	index of axis in question
-------------	---------------------------

## 5.21.3.5 get\_axis\_n\_points()

```
int interpolator_base::get_axis_n_points (
    int axis )
```

Get the number of supporting points for the given axis.

## Parameters

<i>axis</i>	index of axis in question
-------------	---------------------------

5.21.3.6 `get_n_points_total()`

```
uint64_t interpolator_base::get_n_points_total ( )
```

Get the total number of supporting points in parameter space.

## Returns

the total number of supporting points

5.21.3.7 `get_n_points_used()`

```
uint64_t interpolator_base::get_n_points_used ( )
```

Get the number of supporting points used (evaluated through `supporting_point_evaluator`) The number is equal to `n_points_total` for static interpolation methods.

## Returns

the number of supporting points used

5.21.3.8 `init()`

```
int interpolator_base::init ( ) [virtual]
```

Initialize interpolator, perform internal sanity checks unavailable at construction time.

## Returns

int 0 if successful

Reimplemented in [multilinear\\_static\\_cpu\\_interpolator2< index\\_t, value\\_t, N\\_DIMS, N\\_OPS >](#), [multilinear\\_static\\_gpu\\_interpolator2< index\\_t, value\\_t, N\\_DIMS, N\\_OPS >](#), and [linear\\_static\\_cpu\\_interpolator< index\\_t, N\\_DIMS, N\\_OPS >](#).

5.21.3.9 `interpolate()`

```
virtual int interpolator_base::interpolate (
    const std::vector< double > & point,
    std::vector< double > & values ) [pure virtual]
```

Compute interpolation for all operators at the given point.

**Parameters**

in	<i>point</i>	Coordinates in parametrization space
out	<i>values</i>	Interpolated values

**Returns**

0 if interpolation is successful

Implemented in [multilinear\\_interpolator\\_base< index\\_t, value\\_t, N\\_DIMS, N\\_OPS >](#), and [linear\\_cpu\\_interpolator\\_base< index\\_t, N\\_DIMS, N\\_OPS >](#).

**5.21.3.10 interpolate\_with\_derivatives()**

```
virtual int interpolator_base::interpolate_with_derivatives (
    const std::vector< double > & points,
    const std::vector< int > & points_idxs,
    std::vector< double > & values,
    std::vector< double > & derivatives ) [pure virtual]
```

Compute interpolation and its gradient for all operators at every specified point.

**Parameters**

in	<i>points</i>	Array of coordinates in parametrization space
in	<i>points_idx</i> s	Indexes of points in the points array which are marked for interpolation
out	<i>values</i>	Interpolated values
out	<i>derivatives</i>	Interpolation gradients

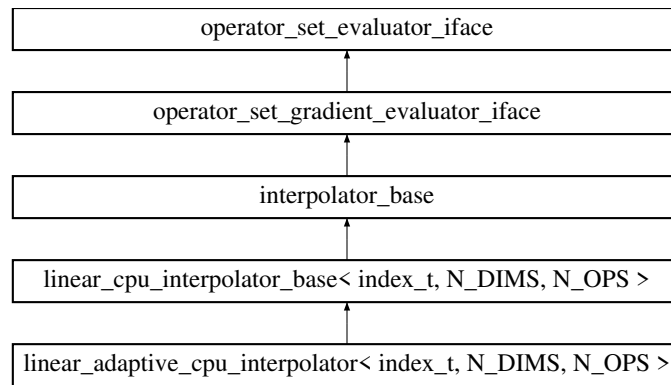
**Returns**

0 if interpolation is successful

Implemented in [multilinear\\_interpolator\\_base< index\\_t, value\\_t, N\\_DIMS, N\\_OPS >](#), [multilinear\\_adaptive\\_cpu\\_interpolator2< index\\_t, value\\_t, N\\_DIMS, N\\_OPS >](#), and [linear\\_cpu\\_interpolator\\_base< index\\_t, N\\_DIMS, N\\_OPS >](#).

## 5.22 linear\_adaptive\_cpu\_interpolator< index\_t, N\_DIMS, N\_OPS > Class Template Reference

Inheritance diagram for linear\_adaptive\_cpu\_interpolator< index\_t, N\_DIMS, N\_OPS >:



## Public Member Functions

- **linear\_adaptive\_cpu\_interpolator** (operator\_set\_evaluator\_iface \*base\_points\_generator, const std::vector< int > &axesPoints, const std::vector< double > &axesMin, const std::vector< double > &axesMax)

## Public Attributes

- std::unordered\_map< index\_t, std::array< double, N\_OPS > > [point\\_data](#)  
adaptive storage: the values of operators at supporting points actually required

## Additional Inherited Members

### 5.22.1 Detailed Description

```

template<typename index_t, int N_DIMS, int N_OPS>
class linear_adaptive_cpu_interpolator< index_t, N_DIMS, N_OPS >

```

Adaptive piecewise linear interpolator

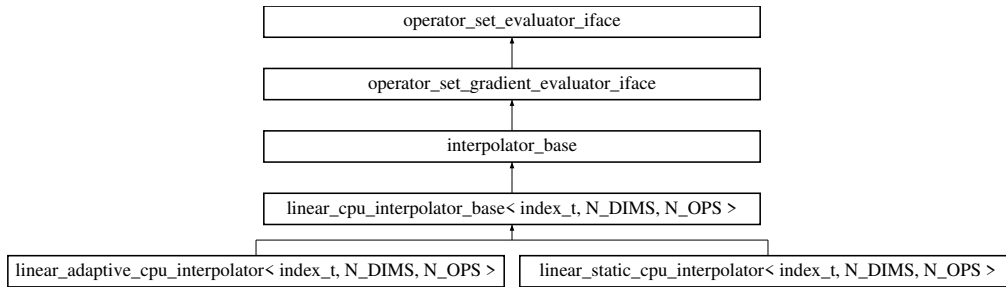
#### Template Parameters

<i>index_t</i>	index type used for supporting point indexing
<i>N_DIMS</i>	The number of dimensions in paramter space
<i>N_OPS</i>	The number of operators to be interpolated

## 5.23 linear\_cpu\_interpolator\_base< index\_t, N\_DIMS, N\_OPS > Class Template Reference

Interpolator base for static/adaptive piecewise linear interpolator.

Inheritance diagram for linear\_cpu\_interpolator\_base< index\_t, N\_DIMS, N\_OPS >:



## Public Member Functions

- [linear\\_cpu\\_interpolator\\_base](#) (operator\_set\_evaluator\_iface \*[supporting\\_point\\_evaluator](#), const std::vector< int > &[axes\\_points](#), const std::vector< double > &[axes\\_min](#), const std::vector< double > &[axes\\_max](#))  
Construct an interpolator with specified parametrization space.
- int [get\\_n\\_dims](#) ()  
Get the number of dimensions in interpolation space.
- int [get\\_n\\_ops](#) ()  
Get the number of operators to be interpolated.
- int [interpolate](#) (const std::vector< value\_t > &point, std::vector< value\_t > &values) override  
Compute interpolation for all operators at the given point.
- int [interpolate\\_with\\_derivatives](#) (const std::vector< double > &points, const std::vector< int > &points\_idx, std::vector< double > &interp\_values, std::vector< double > &derivatives) override  
Compute interpolation and its gradient for all operators at every specified point.

## Protected Member Functions

- void [find\\_hypercube](#) (const std::vector< double > &points, std::array< int, N\_DIMS > &hypercube, std::array< double, N\_DIMS > &scaled\_point, const int point\_index=0)  
Given the coordinate of a point, the function computes the hypercube where the point is located and its scaled coordinate inside the hypercube.
- void [find\\_simplex](#) (const std::array< int, N\_DIMS > &hypercube, const std::array< double, N\_DIMS > &scaled\_point, std::array< int, N\_DIMS > &tri\_order, std::array< std::array< int, N\_DIMS >, N\_DIMS+1 > &simplex)  
Compute which simplex the given point is located in using standard triangulation.
- virtual void [get\\_supporting\\_point](#) (const std::array< int, N\_DIMS > &vertex, std::array< double, N\_OPS > &values)=0  
Get values of operators at the given supporting point Implementation depends on underlying storage. If static storage is used, the function simply reads operator values of the given supporting point from the the storage. If adaptive storage is used, the function checks whether the values were computed before, if yes, the value is directly returned; if not, the function computes the values, stores them and then returns.
- index\_t [get\\_index\\_from\\_vertex](#) (const std::array< int, N\_DIMS > &vertex)  
Given a supporting point, compute its index.
- void [get\\_point\\_from\\_vertex](#) (const std::array< int, N\_DIMS > &vertex, std::vector< double > &point)  
Transfer a vertex to its coordinates.

## Protected Attributes

- std::array< std::array< int, N\_DIMS >, N\_DIMS+1 > [standard\\_simplex](#)  
a standard simplex
- std::array< index\_t, N\_DIMS > [axes\\_mult](#)
- int [transform\\_last\\_axis](#)  
multiplication factor used for transferring supporting point to point index

### 5.23.1 Detailed Description

```
template<typename index_t, int N_DIMS, int N_OPS>
class linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >
```

Interpolator base for static/adaptive piecewise linear interpolator.

#### Template Parameters

<i>index_t</i>	index type used for supporting point indexing
<i>N_DIMS</i>	The number of dimensions in paramter space
<i>N_OPS</i>	The number of operators to be interpolated

### 5.23.2 Constructor & Destructor Documentation

#### 5.23.2.1 linear\_cpu\_interpolator\_base()

```
template<typename index_t , int N_DIMS, int N_OPS>
linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::linear_cpu_interpolator_base (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )
```

Construct an interpolator with specified parametrization space.

#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

### 5.23.3 Member Function Documentation

#### 5.23.3.1 find\_hypercube()

```
template<typename index_t , int N_DIMS, int N_OPS>
void linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::find_hypercube (
    const std::vector< double > & points,
```

```
std::array< int, N_DIMS > & hypercube,
std::array< double, N_DIMS > & scaled_point,
const int point_index = 0 ) [protected]
```

Given the coordinate of a point, the function computes the hypercube where the point is located and its scaled coordinate inside the hypercube.

#### Parameters

in	<i>points</i>	The array of coordinates of points
out	<i>hypercube</i>	The lower-left vertex of the hypercube
out	<i>scaled_point</i>	The scaled coordinate of the given point inside the hypercube
in	<i>point_index</i>	Index of the point in the std::vector points The argument point_index is used only when std::vector points consists of multiple points.

#### 5.23.3.2 find\_simplex()

```
template<typename index_t , int N_DIMS, int N_OPS>
void linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::find_simplex (
    const std::array< int, N_DIMS > & hypercube,
    const std::array< double, N_DIMS > & scaled_point,
    std::array< int, N_DIMS > & tri_order,
    std::array< std::array< int, N_DIMS >, N_DIMS+1 > & simplex ) [protected]
```

Compute which simplex the given point is located in using standard triangulation.

#### Parameters

in	<i>hypercube</i>	The lower-left vertex of the hypercube
in	<i>scaled_point</i>	The scaled coordinate of the given point inside the hypercube
out	<i>tri_order</i>	The order of the scaled coordinate which is used for <ol style="list-style-type: none"> <li>1. finding simplex for standard triangulation</li> <li>2. computing weights of the barycentric interpolation</li> </ol>
out	<i>simplex</i>	An array of vertices which forms simplex in N_DIMS-dimensional space

#### 5.23.3.3 get\_index\_from\_vertex()

```
template<typename index_t , int N_DIMS, int N_OPS>
index_t linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::get_index_from_vertex (
    const std::array< int, N_DIMS > & vertex ) [protected]
```

Given a supporting point, compute its index.

This function is used as a hash for std::array<int, N\_DIMS>.

**Parameters**

in	<i>vertex</i>	The indexes of coordinates the given supporting point along axes
----	---------------	--

**Returns**

The index of point among all supporting point

**5.23.3.4 get\_point\_from\_vertex()**

```
template<typename index_t , int N_DIMS, int N_OPS>
void linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::get_point_from_vertex (
    const std::array< int, N_DIMS > & vertex,
    std::vector< double > & point ) [protected]
```

Transfer a vertex to its coordinates.

**Parameters**

in	<i>vertex</i>	The indexes of the given supporting point along axes
out	<i>point</i>	The coordinates of the supporting point

**5.23.3.5 get\_supporting\_point()**

```
template<typename index_t , int N_DIMS, int N_OPS>
virtual void linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::get_supporting_point (
    const std::array< int, N_DIMS > & vertex,
    std::array< double, N_OPS > & values ) [protected], [pure virtual]
```

Get values of operators at the given supporting point Implementation depends on underlying storage. If static storage is used, the function simply reads operator values of the given supporting point from the the storage. If adaptive storage is used, the function checks whether the values were computed before, if yes, the value is directly returned; if not, the function computes the values, stores them and then returns.

**Parameters**

in	<i>vertex</i>	The indexes of coordinates the given supporting point along axes
out	<i>values</i>	The operator values at the given point

**5.23.3.6 interpolate()**

```
template<typename index_t , int N_DIMS, int N_OPS>
int linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::interpolate (
```

```
const std::vector< value_t > & point,
std::vector< value_t > & values ) [override], [virtual]
```

Compute interpolation for all operators at the given point.

#### Parameters

in	<i>point</i>	Coordinates in parametrization space
out	<i>values</i>	Interpolated values

#### Returns

0 if interpolation is successful

Implements [interpolator\\_base](#).

#### 5.23.3.7 interpolate\_with\_derivatives()

```
template<typename index_t , int N_DIMS, int N_OPS>
int linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::interpolate_with_derivatives (
    const std::vector< double > & points,
    const std::vector< int > & points_idx,
    std::vector< double > & interp_values,
    std::vector< double > & derivatives ) [override], [virtual]
```

Compute interpolation and its gradient for all operators at every specified point.

#### Parameters

in	<i>points</i>	Array of coordinates in parametrization space
in	<i>points_idx</i>	Indexes of points in the points array which are marked for interpolation
out	<i>values</i>	Interpolated values
out	<i>derivatives</i>	Interpolation gradients

#### Returns

0 if interpolation is successful

Implements [interpolator\\_base](#).

### 5.23.4 Member Data Documentation

#### 5.23.4.1 transform\_last\_axis

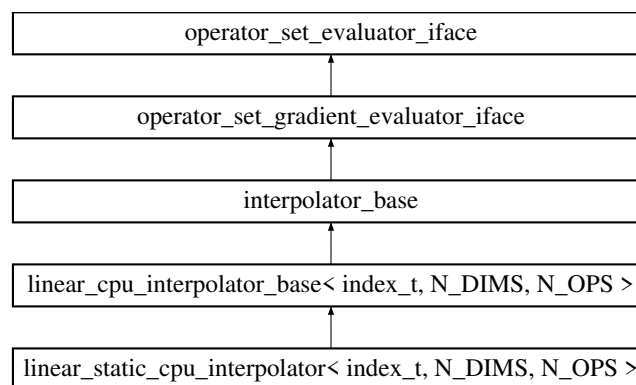
```
template<typename index_t , int N_DIMS, int N_OPS>
int linear_cpu_interpolator_base< index_t, N_DIMS, N_OPS >::transform_last_axis [protected]
```

multiplication factor used for transferring supporting point to point index

apply transformation  $z'=1-z$  for the last axis

### 5.24 linear\_static\_cpu\_interpolator< index\_t, N\_DIMS, N\_OPS > Class Template Reference

Inheritance diagram for linear\_static\_cpu\_interpolator< index\_t, N\_DIMS, N\_OPS >:



#### Public Member Functions

- [linear\\_static\\_cpu\\_interpolator](#) (operator\_set\_evaluator\_iface \*[supporting\\_point\\_evaluator](#), const std::vector< int > &[axes\\_points](#), const std::vector< double > &[axes\\_min](#), const std::vector< double > &[axes\\_max](#))  
Construct the interpolator with specified parametrization space.
- int [init](#) () override  
Initialize the interpolator by computing all values of supporting points if the storage was not already initialized.

#### Public Attributes

- std::vector< double > [point\\_data](#)  
static storage: the values of operators at all supporting points

#### Additional Inherited Members

#### 5.24.1 Detailed Description

```
template<typename index_t, int N_DIMS, int N_OPS>
class linear_static_cpu_interpolator< index_t, N_DIMS, N_OPS >
```

Static piecewise linear interpolator

## Template Parameters

<i>index_t</i>	index type used for supporting point indexing
<i>N_DIMS</i>	The number of dimensions in paramter space
<i>N_OPS</i>	The number of operators to be interpolated

## 5.24.2 Constructor &amp; Destructor Documentation

5.24.2.1 `linear_static_cpu_interpolator()`

```
template<typename index_t , int N_DIMS, int N_OPS>
linear_static_cpu_interpolator< index_t, N_DIMS, N_OPS >::linear_static_cpu_interpolator (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )
```

Construct the interpolator with specified parametrization space.

## Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

## 5.24.3 Member Function Documentation

5.24.3.1 `init()`

```
template<typename index_t , int N_DIMS, int N_OPS>
int linear_static_cpu_interpolator< index_t, N_DIMS, N_OPS >::init ( ) [override], [virtual]
```

Initialize the interpolator by computing all values of supporting points if the storage was not already initialized.

## Returns

int 0 if successful

Reimplemented from [interpolator\\_base](#).

## 5.25 linalg::Matrix< T > Class Template Reference

### Public Types

- typedef T **Type**

### Public Member Functions

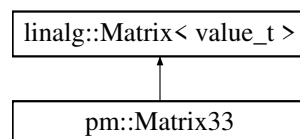
- **Matrix** (index\_t \_M, index\_t \_N)
- **Matrix** (const [Matrix](#)< T > &m)
- **Matrix** (const std::valarray< T > &v, const index\_t \_M, const index\_t \_N)
- index\_t **getIndex** (index\_t i, index\_t j) const
- [Matrix](#)< T > **transpose** () const
- void **transposeInplace** ()
- bool **inv** ()
- bool **lu** (std::valarray< size\_t > &ri, T \*pDet)
- T **det** () const

### Public Attributes

- int **M**
- int **N**
- std::valarray< T > **values**
- std::gslice **g**

## 5.26 pm::Matrix33 Class Reference

Inheritance diagram for pm::Matrix33:



### Public Types

- typedef [Matrix](#) **Base**

### Public Member Functions

- **Matrix33** (value\_t kx)
- **Matrix33** (value\_t kx, value\_t ky, value\_t kz)
- **Matrix33** (std::valarray< value\_t > \_m)

## Static Public Attributes

- static const index\_t **N** = ND \* ND

## Additional Inherited Members

## 5.27 pm::mech\_operators Class Reference

### Public Member Functions

- **~mech\_operators** ()
- void **init** (conn\_mesh \* \_mesh, pm\_discretizer \* \_discr, uint8\_t \_P\_VAR, uint8\_t \_Z\_VAR, uint8\_t \_U\_VAR, uint8\_t \_N\_VARS, uint8\_t \_N\_OPS, uint8\_t \_NC, uint8\_t \_ACC\_OP, uint8\_t \_FLUX\_OP, uint8\_t \_GRAV\_OP)
- std::vector< value\_t > **eval\_flux** (int cell\_id, int face\_id, const std::vector< value\_t > &X)
- void **eval\_fluxes** (const std::vector< value\_t > &X, const std::vector< value\_t > &bc\_rhs, const std::vector< value\_t > &op\_vals\_arr)
- void **eval\_stresses** (const std::vector< value\_t > &X, const std::vector< value\_t > &bc\_rhs, const std::vector< value\_t > &op\_vals\_arr)
- void **eval\_porosities** (const std::vector< value\_t > &X, const std::vector< value\_t > &bc\_rhs)

### Public Attributes

- std::vector< std::vector< std::vector< value\_t > > > **fluxes**
- std::vector< std::vector< value\_t > > **pressures**
- std::vector< std::array< value\_t, 6 > > **stresses**
- std::vector< std::array< value\_t, 6 > > **total\_stresses**
- std::vector< value\_t > **eps\_vol**
- std::vector< value\_t > **porosities**

### Protected Attributes

- conn\_mesh \* **mesh**
- pm\_discretizer \* **discr**
- uint8\_t **P\_VAR**
- uint8\_t **Z\_VAR**
- uint8\_t **U\_VAR**
- uint8\_t **N\_VARS**
- uint8\_t **N\_OPS**
- uint8\_t **NC**
- uint8\_t **ACC\_OP**
- uint8\_t **FLUX\_OP**
- uint8\_t **GRAV\_OP**
- std::map< uint8\_t, Matrix > **pre\_N**
- std::map< uint8\_t, Matrix > **pre\_R**
- std::map< uint8\_t, Matrix > **pre\_Ft**
- std::map< uint8\_t, Matrix > **pre\_F**

## Static Protected Attributes

- static const uint8\_t **ND** = 3
- static const uint8\_t **NT** = 4
- static const uint8\_t **N\_TRANS\_SQ** = NT \* NT

## 5.28 ms\_well Class Reference

Base class for multi-segmented well.

### Public Member Functions

- void **init\_rate\_parameters** (int n\_vars\_, std::vector< std::string > phase\_names\_, operator\_set\_gradient↵\_evaluator\_iface \*rate\_evaluator\_, int thermal\_=0)
- int **add\_to\_jacobian** (double dt, std::vector< value\_t > &X, value\_t \*jac\_well\_head, std::vector< value\_t > &RHS)
- int **add\_to\_csr\_jacobian** (double dt, std::vector< value\_t > &X, value\_t \*jac\_well\_head, std::vector< value\_t > &RHS)
- int **check\_constraints** (double dt, std::vector< value\_t > &X)
- int **calc\_rates** (std::vector< value\_t > &X, std::vector< value\_t > &op\_vals\_arr, std::unordered\_map< std::↵string, std::vector< value\_t >> &time\_data)
- int **calc\_rates\_velocity** (std::vector< value\_t > &X, std::vector< value\_t > &op\_vals\_arr, std::unordered↵\_map< std::string, std::vector< value\_t >> &time\_data, index\_t n\_blocks)
- int **initialize\_control** (std::vector< value\_t > &X)

### Public Attributes

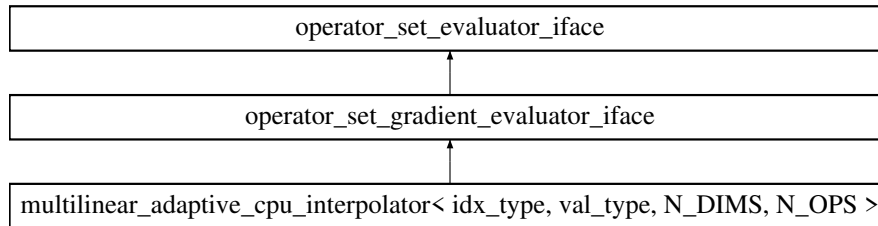
- std::vector< std::tuple< index\_t, index\_t, value\_t > > **perforations**
- value\_t **segment\_volume**
- value\_t **segment\_transmissibility**
- value\_t **well\_head\_depth**
- value\_t **well\_body\_depth**
- value\_t **segment\_depth\_increment**
- value\_t **segment\_diameter**
- value\_t **segment\_roughness**
- index\_t **well\_head\_idx**
- index\_t **well\_body\_idx**
- index\_t **well\_head\_idx\_conn**
- [well\\_control\\_iface](#) \* **control**
- [well\\_control\\_iface](#) \* **constraint**
- operator\_set\_evaluator\_iface \* **rate\_evaluator**
- std::string **name**
- std::vector< std::string > **phase\_names**
- std::vector< value\_t > **state**
- std::vector< value\_t > **state\_neighbour**
- std::vector< value\_t > **rates**
- int **n\_vars**
- int **n\_segments**
- int **n\_phases**
- int **thermal**

## 5.28.1 Detailed Description

Base class for multi-segmented well.

## 5.29 multilinear\_adaptive\_cpu\_interpolator&lt; idx\_type, val\_type, N\_DIMS, N\_OPS &gt; Class Template Reference

Inheritance diagram for multilinear\_adaptive\_cpu\_interpolator< idx\_type, val\_type, N\_DIMS, N\_OPS >:



## Public Member Functions

- **multilinear\_adaptive\_cpu\_interpolator** (operator\_set\_evaluator\_iface \*base\_points\_generator, std::vector< index\_t > &axis\_resolution, std::vector< value\_t > &axis\_min, std::vector< value\_t > &axis\_max)
- int **benchmark** (index\_t n\_points, index\_t n\_blocks, value\_t param\_space\_frac, index\_t n\_unique\_bodies)
- int **evaluate\_with\_derivatives** (const std::vector< value\_t > &state, const std::vector< index\_t > &block\_idx, std::vector< value\_t > &values, std::vector< value\_t > &derivatives)
- int **evaluate** (const std::vector< value\_t > &state, std::vector< value\_t > &values)
- body\_data\_it\_t **add\_body\_from\_points** (const value\_t \*axis\_values, idx\_type body\_idx)
- int **get\_resolution** ()
- value\_t **get\_axis\_min** (int axis)
- value\_t **get\_axis\_max** (int axis)
- uint64\_t **get\_n\_interpolations** ()
- uint64\_t **get\_n\_points\_used** ()
- uint64\_t **get\_n\_points\_total** ()
- uint64\_t **get\_n\_hypercubes\_used** ()
- uint64\_t **get\_n\_hypercubes\_total** ()
- double **get\_interpolation\_timer** ()
- double **get\_generation\_timer** ()
- double **get\_point\_generation\_timer** ()
- int **clear\_body\_data** ()
- int **clear** ()

## Public Attributes

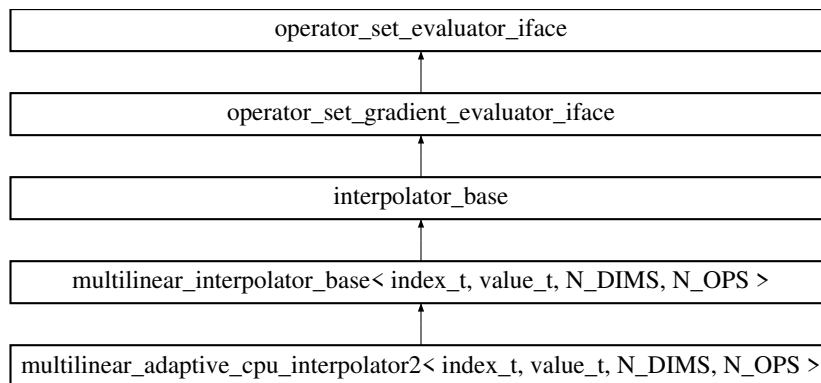
- std::array< unsigned int, N\_DIMS > **axis\_points**
- std::array< val\_type, N\_DIMS > **axis\_min**
- std::array< val\_type, N\_DIMS > **axis\_max**
- val\_type **axis\_step** [N\_DIMS]
- val\_type **axis\_step\_inv** [N\_DIMS]
- idx\_type **axis\_mult** [N\_DIMS]
- idx\_type **axis\_body\_mult** [N\_DIMS]

- `operator_set_evaluator_iface * base_points_generator`
- `std::unordered_map< idx_type, std::vector< val_type > > point_data`
- `std::unordered_map< idx_type, std::vector< val_type > > body_data`
- `std::vector< std::vector< value_t > > body_vertex_axes_values`
- `std::vector< value_t > new_ops_values`
- `std::vector< val_type > new_ops_values_interp`
- `long long n_interpolations`
- `double interpolation_timer`
- `double body_generation_timer`
- `double point_generation_timer`

### 5.30 `multilinear_adaptive_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >` Class Template Reference

Piecewise multilinear interpolator with adaptive storage.

Inheritance diagram for `multilinear_adaptive_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >`:



#### Public Member Functions

- `multilinear_adaptive_cpu_interpolator2` (`operator_set_evaluator_iface *supporting_point_evaluator`, `const std::vector< int > &axes_points`, `const std::vector< double > &axes_min`, `const std::vector< double > &axes_max`)

*Construct the interpolator with specified parametrization space.*

#### Public Attributes

- `std::unordered_map< index_t, point_data_t > point_data`

*adaptive point storage: the values of operators at requested supporting points Storage is grown dynamically in the process of simulation. Only supporting points that are required for interpolation are computed and added*

## Protected Member Functions

- const [point\\_data\\_t](#) & [get\\_point\\_data](#) (const index\_t point\_index)  
*Get values of operators at a given point Provide a reference to correct location in the adaptive point storage. If the point is not found, compute it first, and then return the reference.*
- const [hypercube\\_data\\_t](#) & [get\\_hypercube\\_data](#) (const index\_t hypercube\_index)  
*Get values of operators at all vertices of the hypercube. Provide a reference to correct location in the adaptive hypercube storage. If the hypercube is not found, compute it first, and then return the reference.*
- int [interpolate\\_with\\_derivatives](#) (const std::vector< double > &points, const std::vector< int > &points\_idx, std::vector< double > &values, std::vector< double > &derivatives) override  
*Compute interpolation and its gradient for all operators at every specified point.*

## Protected Attributes

- std::unordered\_map< index\_t, [hypercube\\_data\\_t](#) > [hypercube\\_data](#)  
*adaptive hypercube storage: the values of operators at every vertex of requested hypercubes Storage is grown dynamically in the process of simulation Only hypercubes that are required for interpolation are computed and added*

## Additional Inherited Members

### 5.30.1 Detailed Description

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
class multilinear_adaptive_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >
```

Piecewise multilinear interpolator with adaptive storage.

#### Template Parameters

<i>index_t</i>	type used for indexing of supporting points and hypercubes
<i>value_t</i>	value type used for supporting point storage, hypercube storage and interpolation
<i>N_DIMS</i>	The number of dimensions in parameter space
<i>N_OPS</i>	The number of operators to be interpolated

### 5.30.2 Constructor & Destructor Documentation

#### 5.30.2.1 multilinear\_adaptive\_cpu\_interpolator2()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
multilinear_adaptive_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >::multilinear_adaptive_cpu_interpolator2 (
    operator_set_evaluator_iface * supporting_point_evaluator,
```

```
const std::vector< int > & axes_points,
const std::vector< double > & axes_min,
const std::vector< double > & axes_max )
```

Construct the interpolator with specified parametrization space.

#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

### 5.30.3 Member Function Documentation

#### 5.30.3.1 get\_hypercube\_data()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
const hypercube\_data\_t& multilinear\_adaptive\_cpu\_interpolator2< index_t, value_t, N_DIMS, N_OPS >::get_hypercube_data (
    const index_t hypercube_index ) [protected], [virtual]
```

Get values of operators at all vertices of the hypercube. Provide a reference to correct location in the adaptive hypercube storage. If the hypercube is not found, compute it first, and then return the reference.

#### Parameters

in	<i>hypercube_index</i>	index of hypercube
----	------------------------	--------------------

#### Returns

operator values at all vertices of the hypercube

Implements [multilinear\\_interpolator\\_base](#)< *index\_t*, *value\_t*, *N\_DIMS*, *N\_OPS* >.

#### 5.30.3.2 get\_point\_data()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
const point\_data\_t& multilinear\_adaptive\_cpu\_interpolator2< index_t, value_t, N_DIMS, N_OPS >::get_point_data (
    const index_t point_index ) [protected]
```

Get values of operators at a given point Provide a reference to correct location in the adaptive point storage. If the point is not found, compute it first, and then return the reference.

## Parameters

in	<i>point_index</i>	index of point
----	--------------------	----------------

## Returns

operator values at given point

## 5.30.3.3 interpolate\_with\_derivatives()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
int multilinear_adaptive_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >::interpolate_↔
with_derivatives (
    const std::vector< double > & points,
    const std::vector< int > & points_idx,
    std::vector< double > & values,
    std::vector< double > & derivatives ) [override], [protected], [virtual]
```

Compute interpolation and its gradient for all operators at every specified point.

## Parameters

in	<i>points</i>	Array of coordinates in parametrization space
in	<i>points_idx</i>	Indexes of points in the points array which are marked for interpolation
out	<i>values</i>	Interpolated values
out	<i>derivatives</i>	Interpolation gradients

## Returns

0 if interpolation is successful

Implements [interpolator\\_base](#).

## 5.30.4 Member Data Documentation

## 5.30.4.1 hypercube\_data

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
std::unordered_map<index_t, hypercube_data_t> multilinear_adaptive_cpu_interpolator2< index_↔
_t, value_t, N_DIMS, N_OPS >::hypercube_data [protected]
```

adaptive hypercube storage: the values of operators at every vertex of requested hypercubes Storage is grown dynamically in the process of simulation Only hypercubes that are required for interpolation are computed and added

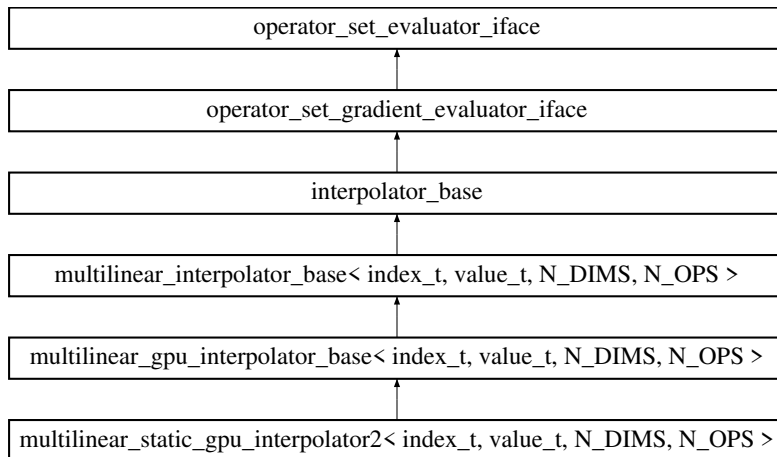
In fact it is an excess storage used to reduce memory accesses during interpolation. Here all values of all vertexes of requested hypercube are stored consecutively and are accessed via a single index Usage of point\_data for interpolation directly would require N\_VERTS memory accesses (>1000 accesses for 10-dimensional space)

•

## 5.31 `multilinear_gpu_interpolator_base< index_t, value_t, N_DIMS, N_OPS >` Class Template Reference

Piecewise multilinear GPU interpolator base class.

Inheritance diagram for `multilinear_gpu_interpolator_base< index_t, value_t, N_DIMS, N_OPS >`:



### Public Member Functions

- `multilinear_gpu_interpolator_base` (`operator_set_evaluator_iface *supporting_point_evaluator`, `const std::vector< int > &axes_points`, `const std::vector< double > &axes_min`, `const std::vector< double > &axes_max`)

*Construct the interpolator with specified parametrization space.*

### Protected Attributes

- `const thrust::device_vector< value_t > axes_min_d`  
*minimum at each axis in value\_t type*

### Additional Inherited Members

#### 5.31.1 Detailed Description

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
class multilinear_gpu_interpolator_base< index_t, value_t, N_DIMS, N_OPS >
```

Piecewise multilinear GPU interpolator base class.

Introduces and initialize basic interpolation data on GPU device

#### Template Parameters

<code>index_t</code>	type used for indexing of supporting points and hypercubes
<code>value_t</code>	value type used for supporting point storage, hypercube storage and interpolation
<code>N_DIMS</code>	The number of dimensions in paramter space
<code>N_OPS</code>	The number of operators to be interpolated

### 5.31.2 Constructor & Destructor Documentation

#### 5.31.2.1 multilinear\_gpu\_interpolator\_base()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
multilinear_gpu_interpolator_base< index_t, value_t, N_DIMS, N_OPS >::multilinear_gpu_interpolator_base (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )
```

Construct the interpolator with specified parametrization space.

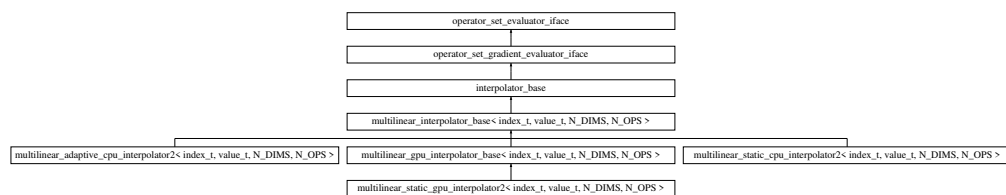
#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

## 5.32 multilinear\_interpolator\_base< index\_t, value\_t, N\_DIMS, N\_OPS > Class Template Reference

Interpolator base for static/adaptive piecewise multilinear interpolator.

Inheritance diagram for multilinear\_interpolator\_base< index\_t, value\_t, N\_DIMS, N\_OPS >:



### Public Types

- typedef std::array< value\_t, N\_OPS > [point\\_data\\_t](#)  
values of all operators at a given (supporting) point
- typedef std::vector< double > [point\\_coordinates\\_t](#)  
coordinates of a given point in *N\_DIMS*-dimensional space
- typedef std::array< int, N\_DIMS > [point\\_axes\\_index\\_t](#)  
indexes of axes of point in parametrized space for each axis
- typedef std::array< value\_t, N\_VERTS \* N\_OPS > [hypercube\\_data\\_t](#)  
type for keeping values of all operators at all vertexes of a hypercube
- typedef std::array< index\_t, N\_VERTS > [hypercube\\_points\\_index\\_t](#)  
type for indexing vertexes of a hypercube

## Public Member Functions

- [multilinear\\_interpolator\\_base](#) (operator\_set\_evaluator\_iface \*[supporting\\_point\\_evaluator](#), const std::vector< int > &[axes\\_points](#), const std::vector< double > &[axes\\_min](#), const std::vector< double > &[axes\\_max](#))  
*Construct the interpolator with specified parametrization space.*
- int [get\\_n\\_dims](#) ()  
*Get the number of dimensions in interpolation space.*
- int [get\\_n\\_ops](#) ()  
*Get the number of operators to be interpolated.*
- int [interpolate](#) (const std::vector< double > &point, std::vector< double > &values) override  
*Compute interpolation for all operators at the given point.*
- int [interpolate\\_with\\_derivatives](#) (const double \*point, double \*values, double \*derivatives)  
*Compute interpolation and its gradient for all operators at the given point point.*
- int [interpolate\\_with\\_derivatives](#) (const std::vector< double > &points, const std::vector< int > &points\_idx, std::vector< double > &values, std::vector< double > &derivatives) override  
*Compute interpolation and its gradient for all operators at every specified point.*

## Static Public Attributes

- static const uint16\_t [N\\_VERTS](#) = (1 << N\_DIMS)  
*number of vertexes in interpolation hypercube - N\_DIMS-th power of 2*

## Protected Member Functions

- void [get\\_point\\_coordinates](#) (index\_t point\_index, [point\\_coordinates\\_t](#) &coordinates)  
*Get point coordinates in space for given point index.*
- void [get\\_hypercube\\_points](#) (index\_t index, [hypercube\\_points\\_index\\_t](#) &hypercube\_points)  
*Get indexes of all vertices for given hypercube.*
- virtual const [hypercube\\_data\\_t](#) & [get\\_hypercube\\_data](#) (const index\_t hypercube\_index)=0  
*Get values of operators at all vertices of the hypercube Implementation depends on underlying storage.*

## Protected Attributes

- const std::vector< value\_t > [axes\\_min\\_internal](#)  
*minimum at each axis in value\_t type*
- const std::vector< value\_t > [axes\\_max\\_internal](#)  
*maximum of each axis in value\_t type*
- const std::vector< value\_t > [axes\\_step\\_internal](#)  
*the distance between neighbor supporting points for each axis in value\_t type*
- const std::vector< value\_t > [axes\\_step\\_inv\\_internal](#)  
*inverse of step (to avoid division) in value\_t type*
- std::array< uint64\_t, N\_DIMS > [axis\\_point\\_mult](#)  
*mult factor for each axis (for points) to compute global point index*
- std::array< uint64\_t, N\_DIMS > [axis\\_hypercube\\_mult](#)  
*mult factor for each axis (for hypercubes) to compute global hypercubes index*

### 5.32.1 Detailed Description

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
class multilinear_interpolator_base< index_t, value_t, N_DIMS, N_OPS >
```

Interpolator base for static/adaptive piecewise multilinear interpolator.

Interpolation is performed simultaneously for several functions (operators) in multidimensional parameter space. In order to do that, the space is uniformly parametrized within range of interest. That range along each axis is divided by specific number of equal intervals, forming uniform mesh. Each vertex of the mesh represents a supporting point, where operator values are evaluated exactly. Using data at supporting points, interpolation is performed.

#### Template Parameters

<i>index_t</i>	type used for indexing of supporting points and hypercubes
<i>value_t</i>	value type used for supporting point storage, hypercube storage and interpolation
<i>N_DIMS</i>	The number of dimensions in parameter space
<i>N_OPS</i>	The number of operators to be interpolated

### 5.32.2 Constructor & Destructor Documentation

#### 5.32.2.1 multilinear\_interpolator\_base()

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
multilinear_interpolator_base< index_t, value_t, N_DIMS, N_OPS >::multilinear_interpolator_↵
base (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )
```

Construct the interpolator with specified parametrization space.

#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

### 5.32.3 Member Function Documentation

### 5.32.3.1 `get_hypercube_data()`

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
virtual const hypercube\_data\_t& multilinear\_interpolator\_base< index_t, value_t, N_DIMS, N_OPS
>::get_hypercube_data (
    const index_t hypercube_index ) [protected], [pure virtual]
```

Get values of operators at all vertices of the hypercube Implementation depends on underlying storage.

#### Parameters

in	<i>hypercube_index</i>	index of hypercube
----	------------------------	--------------------

#### Returns

operator values at all vertices of the hypercube

Implemented in [multilinear\\_static\\_cpu\\_interpolator2](#)< [index\\_t](#), [value\\_t](#), [N\\_DIMS](#), [N\\_OPS](#) >, [multilinear\\_static\\_gpu\\_interpolator2](#)< [index\\_t](#), [value\\_t](#), [N\\_DIMS](#), [N\\_OPS](#) >, and [multilinear\\_adaptive\\_cpu\\_interpolator2](#)< [index\\_t](#), [value\\_t](#), [N\\_DIMS](#), [N\\_OPS](#) >.

### 5.32.3.2 `get_hypercube_points()`

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
void multilinear\_interpolator\_base< index_t, value_t, N_DIMS, N_OPS >::get_hypercube_points (
    index_t index,
    hypercube\_points\_index\_t & hypercube_points ) [inline], [protected]
```

Get indexes of all vertices for given hypercube.

#### Parameters

in	<i>index</i>	index of the hyporcube
out	<i>hypercube_points</i>	indexes of all vertices of hypercube

### 5.32.3.3 `get_point_coordinates()`

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
void multilinear\_interpolator\_base< index_t, value_t, N_DIMS, N_OPS >::get_point_coordinates (
    index_t point_index,
    point\_coordinates\_t & coordinates ) [inline], [protected]
```

Get point coordinates in space for given point index.

## Parameters

in	<i>point_index</i>	index of the point
out	<i>coordinates</i>	coordinates along all axes

## 5.32.3.4 interpolate()

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
int multilinear_interpolator_base< index_t, value_t, N_DIMS, N_OPS >::interpolate (
    const std::vector< double > & point,
    std::vector< double > & values ) [override], [virtual]
```

Compute interpolation for all operators at the given point.

## Parameters

in	<i>point</i>	Coordinates in parametrization space
out	<i>values</i>	Interpolated values

## Returns

0 if interpolation is successful

Implements [interpolator\\_base](#).

## 5.32.3.5 interpolate\_with\_derivatives() [1/2]

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
int multilinear_interpolator_base< index_t, value_t, N_DIMS, N_OPS >::interpolate_with_↵
derivatives (
    const double * point,
    double * values,
    double * derivatives )
```

Compute interpolation and its gradient for all operators at the given point point.

## Parameters

in	<i>points</i>	Coordinates of a point where interpolation is requested
out	<i>values</i>	Interpolated values
out	<i>derivatives</i>	Interpolation gradients

**Returns**

0 if interpolation is successful

**5.32.3.6 interpolate\_with\_derivatives()** [2/2]

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
int multilinear_interpolator_base< index_t, value_t, N_DIMS, N_OPS >::interpolate_with_↵
derivatives (
    const std::vector< double > & points,
    const std::vector< int > & points_idx,
    std::vector< double > & values,
    std::vector< double > & derivatives ) [override], [virtual]
```

Compute interpolation and its gradient for all operators at every specified point.

**Parameters**

in	<i>points</i>	Array of coordinates in parametrization space
in	<i>points_idx</i>	Indexes of points in the points array which are marked for interpolation
out	<i>values</i>	Interpolated values
out	<i>derivatives</i>	Interpolation gradients

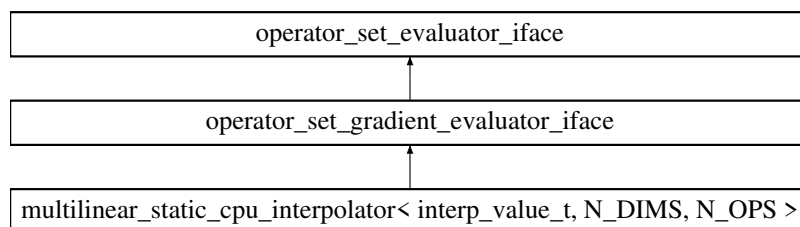
**Returns**

0 if interpolation is successful

Implements [interpolator\\_base](#).

**5.33 multilinear\_static\_cpu\_interpolator< interp\_value\_t, N\_DIMS, N\_OPS > Class Template Reference**

Inheritance diagram for multilinear\_static\_cpu\_interpolator< interp\_value\_t, N\_DIMS, N\_OPS >:

**Public Member Functions**

- **multilinear\_static\_cpu\_interpolator** (operator\_set\_evaluator\_iface \*base\_points\_generator, std::vector< index\_t > &axis\_resolution, std::vector< value\_t > &axis\_min, std::vector< value\_t > &axis\_max)

- int **benchmark** (index\_t n\_points, index\_t n\_blocks, value\_t param\_space\_frac, index\_t n\_unique\_bodies)
- int **evaluate\_with\_derivatives** (const std::vector< value\_t > &state, const std::vector< index\_t > &block\_idx, std::vector< value\_t > &values, std::vector< value\_t > &derivatives)
- int **evaluate\_with\_derivatives\_fake** (const std::vector< value\_t > &state, const std::vector< index\_t > &block\_idx, std::vector< value\_t > &values, std::vector< value\_t > &derivatives)
- int **evaluate** (const std::vector< value\_t > &state, std::vector< value\_t > &values)
- void **get\_point\_state** (interp\_index\_t point\_idx, state\_t &state)
- void **get\_body\_points** (interp\_index\_t body\_idx, body\_data\_points\_t &body\_points)
- int **get\_resolution** ()
- value\_t **get\_axis\_min** (int axis)
- value\_t **get\_axis\_max** (int axis)
- uint64\_t **get\_n\_points\_total** ()
- uint64\_t **get\_n\_hypercubes\_used** ()
- uint64\_t **get\_n\_hypercubes\_total** ()
- int **clear\_body\_data** ()
- int **clear** ()

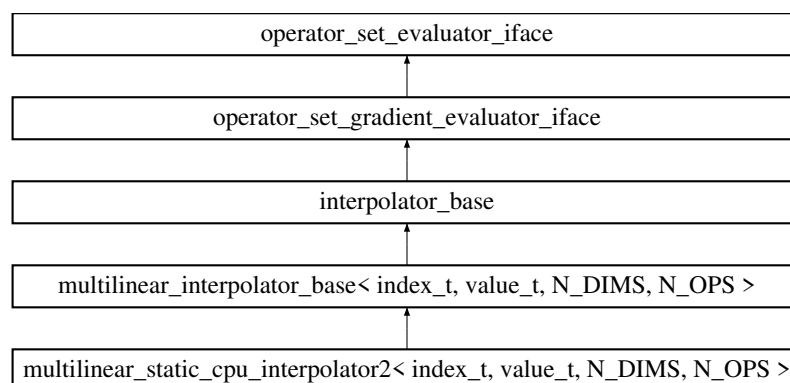
### Public Attributes

- std::array< uint32\_t, N\_DIMS > **axis\_points**
- std::array< interp\_value\_t, N\_DIMS > **axis\_min**
- std::array< interp\_value\_t, N\_DIMS > **axis\_max**
- interp\_value\_t **axis\_step** [N\_DIMS]
- interp\_value\_t **axis\_step\_inv** [N\_DIMS]
- uint64\_t **axis\_mult** [N\_DIMS]
- uint64\_t **axis\_body\_mult** [N\_DIMS]
- operator\_set\_evaluator\_iface \* **base\_points\_generator**
- uint64\_t **n\_interpolations**
- point\_data\_t **point\_data**
- body\_data\_t **body\_data**
- int **fake\_mode**

## 5.34 multilinear\_static\_cpu\_interpolator2< index\_t, value\_t, N\_DIMS, N\_OPS > Class Template Reference

Piecewise multilinear interpolator with static storage.

Inheritance diagram for multilinear\_static\_cpu\_interpolator2< index\_t, value\_t, N\_DIMS, N\_OPS >:



## Public Member Functions

- [multilinear\\_static\\_cpu\\_interpolator2](#) (operator\_set\_evaluator\_iface \*[supporting\\_point\\_evaluator](#), const std::vector< int > &[axes\\_points](#), const std::vector< double > &[axes\\_min](#), const std::vector< double > &[axes\\_max](#))  
Construct the interpolator with specified parametrization space.
- int [init](#) () override  
Initialize the interpolator by:

## Public Attributes

- std::vector< [point\\_data\\_t](#) > [point\\_data](#)  
static point storage: the values of operators at all supporting points

## Protected Member Functions

- const [hypercube\\_data\\_t](#) & [get\\_hypercube\\_data](#) (const index\_t hypercube\_index)  
Get values of operators at all vertices of the hypercube. Simply provide a reference to correct location in static storage  
- all values have been already computed.

## Protected Attributes

- std::vector< [hypercube\\_data\\_t](#) > [hypercube\\_data](#)  
static hypercube storage: the values of operators at every vertex of all hypercubes

## Additional Inherited Members

### 5.34.1 Detailed Description

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
class multilinear_static_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >
```

Piecewise multilinear interpolator with static storage.

Static storage is initialized in [init\(\)](#) method. Two-level storage is used: with operator data at every supporting point and with operator data at all vertices of every hypercube point data may be assigned externally after construction and before [init\(\)](#) call to save time hypercube storage then is initialized only and much faster, as does not involve computation of supporting points, only copying

#### Template Parameters

<a href="#">index_t</a>	type used for indexing of supporting points and hypercubes
<a href="#">value_t</a>	value type used for supporting point storage, hypercube storage and interpolation
<a href="#">N_DIMS</a>	The number of dimensions in paramter space
<a href="#">N_OPS</a>	The number of operators to be interpolated

## 5.34.2 Constructor & Destructor Documentation

### 5.34.2.1 multilinear\_static\_cpu\_interpolator2()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
multilinear_static_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >::multilinear_static_
cpu_interpolator2 (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )
```

Construct the interpolator with specified parametrization space.

#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

## 5.34.3 Member Function Documentation

### 5.34.3.1 get\_hypercube\_data()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
const hypercube_data_t& multilinear_static_cpu_interpolator2< index_t, value_t, N_DIMS, N_OPS
>::get_hypercube_data (
    const index_t hypercube_index ) [protected], [virtual]
```

Get values of operators at all vertices of the hypercube. Simply provide a reference to correct location in static storage - all values have been already computed.

#### Parameters

in	<i>hypercube_index</i>	index of hypercube
----	------------------------	--------------------

#### Returns

operator values at all vertices of the hypercube

Implements [multilinear\\_interpolator\\_base< index\\_t, value\\_t, N\\_DIMS, N\\_OPS >](#).

### 5.34.3.2 init()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
int multilinear\_static\_cpu\_interpolator2< index_t, value_t, N_DIMS, N_OPS >::init ( ) [override],
[virtual]
```

Initialize the interpolator by:

1. computing all values of supporting points (if point\_data storage was not already initialized)
2. populating hypercube static storage from point storage

#### Returns

int 0 if successful

Reimplemented from [interpolator\\_base](#).

## 5.34.4 Member Data Documentation

### 5.34.4.1 hypercube\_data

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
std::vector<hypercube\_data\_t> multilinear\_static\_cpu\_interpolator2< index_t, value_t, N_DIMS,
N_OPS >::hypercube_data [protected]
```

static hypercube storage: the values of operators at every vertex of all hypercubes

In fact it is an excess storage used to reduce memory accesses during interpolation. Here all values of all vertexes of every hypercube are stored consecutively and are accessed via a single index Usage of point\_data for interpolation directly would require N\_VERTS memory accesses (>1000 accesses for 10-dimensional space)

### 5.34.4.2 point\_data

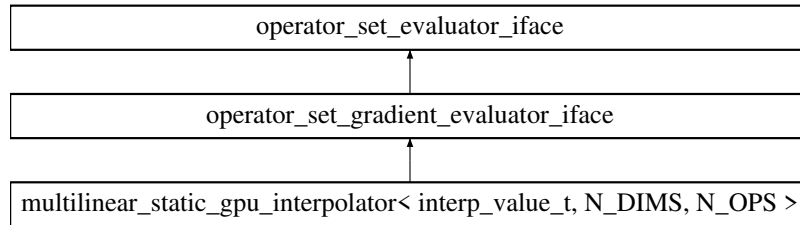
```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
std::vector<point\_data\_t> multilinear\_static\_cpu\_interpolator2< index_t, value_t, N_DIMS, N_OPS >::point_data
```

static point storage: the values of operators at all supporting points

Used to store all computed supporting points and to initialize hypercube\_data

## 5.35 multilinear\_static\_gpu\_interpolator< interp\_value\_t, N\_DIMS, N\_OPS > Class Template Reference

Inheritance diagram for multilinear\_static\_gpu\_interpolator< interp\_value\_t, N\_DIMS, N\_OPS >:



### Public Member Functions

- **multilinear\_static\_gpu\_interpolator** (operator\_set\_evaluator\_iface \*base\_points\_generator, std::vector< index\_t > &axis\_resolution, std::vector< value\_t > &axis\_min, std::vector< value\_t > &axis\_max)
- int **benchmark** (index\_t n\_points, index\_t n\_blocks, value\_t used\_paramspace\_fraction, index\_t n\_unique\_bodies)
- int **evaluate\_with\_derivatives** (const std::vector< value\_t > &state, const std::vector< index\_t > &block\_idx, std::vector< value\_t > &values, std::vector< value\_t > &derivatives)
- virtual int **evaluate\_with\_derivatives\_d** (index\_t n\_blocks, value\_t \*state, index\_t \*block\_idx, value\_t \*values, value\_t \*derivatives)
- int **evaluate** (const std::vector< value\_t > &state, std::vector< value\_t > &values)
- void **get\_point\_state** (interp\_index\_t point\_idx, state\_t &state)
- void **get\_body\_points** (interp\_index\_t body\_idx, body\_data\_points\_t &body\_points)
- int **get\_resolution** ()
- value\_t **get\_axis\_min** (int axis)
- value\_t **get\_axis\_max** (int axis)
- uint64\_t **get\_n\_interpolations** ()
- uint64\_t **get\_n\_points\_used** ()
- uint64\_t **get\_n\_points\_total** ()
- uint64\_t **get\_n\_hypercubes\_used** ()
- uint64\_t **get\_n\_hypercubes\_total** ()
- int **clear\_body\_data** ()
- int **clear** ()

### Public Attributes

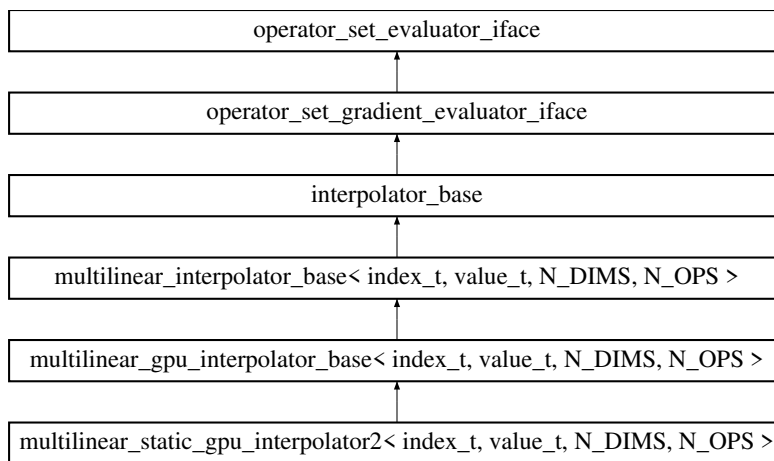
- std::array< uint32\_t, N\_DIMS > **axis\_points**
- std::array< value\_t, N\_DIMS > **axis\_min**
- std::array< value\_t, N\_DIMS > **axis\_max**
- value\_t **axis\_step** [N\_DIMS]
- value\_t **axis\_step\_inv** [N\_DIMS]
- uint64\_t **axis\_mult** [N\_DIMS]
- uint32\_t **axis\_body\_mult** [N\_DIMS]
- operator\_set\_evaluator\_iface \* **base\_points\_generator**
- uint64\_t **n\_interpolations**
- point\_data\_t **point\_data**
- body\_data\_t **body\_data**
- interp\_value\_t \* **body\_data\_gpu**

- value\_t \* **state\_gpu**
- value\_t \* **values\_gpu**
- value\_t \* **derivatives\_gpu**
- index\_t \* **block\_idx\_gpu**
- index\_t **gpu\_data\_size**
- int **fake\_mode**

### 5.36 multilinear\_static\_gpu\_interpolator2< index\_t, value\_t, N\_DIMS, N\_OPS > Class Template Reference

Piecewise multilinear interpolator with static storage.

Inheritance diagram for multilinear\_static\_gpu\_interpolator2< index\_t, value\_t, N\_DIMS, N\_OPS >:



#### Public Member Functions

- [multilinear\\_static\\_gpu\\_interpolator2](#) (operator\_set\_evaluator\_iface \*[supporting\\_point\\_evaluator](#), const std::vector< int > &[axes\\_points](#), const std::vector< double > &[axes\\_min](#), const std::vector< double > &[axes\\_max](#))  
*Construct the interpolator with specified parametrization space.*
- int [init](#) () override  
*Initialize the interpolator by:*

#### Public Attributes

- std::vector< [point\\_data\\_t](#) > [point\\_data](#)  
*static point storage: the values of operators at all supporting points*

#### Protected Member Functions

- const [hypercube\\_data\\_t](#) & [get\\_hypercube\\_data](#) (const index\_t hypercube\_index)  
*Get values of operators at all vertices of the hypercube. Simply provide a reference to correct location in static storage - all values have been already computed.*

## Protected Attributes

- `std::vector< hypercube\_data\_t > hypercube_data`  
*static hypercube storage: the values of operators at every vertex of all hypercubes*

## Additional Inherited Members

### 5.36.1 Detailed Description

```
template<typename index_t, typename value_t, uint8_t N_DIMS, uint8_t N_OPS>
class multilinear_static_gpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >
```

Piecewise multilinear interpolator with static storage.

Static storage is initialized in [init\(\)](#) method. Two-level storage is used: with operator data at every supporting point and with operator data at all vertices of every hypercube point data may be assigned externally after construction and before [init\(\)](#) call to save time hypercube storage then is initialized only and much faster, as does not involve computation of supporting points, only copying

#### Template Parameters

<i>index_t</i>	type used for indexing of supporting points and hypercubes
<i>value_t</i>	value type used for supporting point storage, hypercube storage and interpolation
<i>N_DIMS</i>	The number of dimensions in parameter space
<i>N_OPS</i>	The number of operators to be interpolated

### 5.36.2 Constructor & Destructor Documentation

#### 5.36.2.1 multilinear\_static\_gpu\_interpolator2()

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
multilinear_static_gpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >::multilinear_static_
gpu_interpolator2 (
    operator_set_evaluator_iface * supporting_point_evaluator,
    const std::vector< int > & axes_points,
    const std::vector< double > & axes_min,
    const std::vector< double > & axes_max )
```

Construct the interpolator with specified parametrization space.

#### Parameters

in	<i>supporting_point_evaluator</i>	Object used to compute operators values at supporting points
in	<i>axes_points</i>	Number of supporting points (minimum 2) along axes
in	<i>axes_min</i>	Minimum value for each axis
in	<i>axes_max</i>	Maximum for each axis

### 5.36.3 Member Function Documentation

#### 5.36.3.1 `get_hypercube_data()`

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
const hypercube\_data\_t& multilinear\_static\_gpu\_interpolator2< index_t, value_t, N_DIMS, N_OPS
>::get_hypercube_data (
    const index_t hypercube_index ) [protected], [virtual]
```

Get values of operators at all vertices of the hypercube. Simply provide a reference to correct location in static storage - all values have been already computed.

##### Parameters

in	<i>hypercube_index</i>	index of hypercube
----	------------------------	--------------------

##### Returns

operator values at all vertices of the hypercube

Implements [multilinear\\_interpolator\\_base](#)< *index\_t*, *value\_t*, *N\_DIMS*, *N\_OPS* >.

#### 5.36.3.2 `init()`

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
int multilinear\_static\_gpu\_interpolator2< index_t, value_t, N_DIMS, N_OPS >::init ( ) [override],
[virtual]
```

Initialize the interpolator by:

1. computing all values of supporting points (if *point\_data* storage was not already initialized)
2. populating hypercube static storage from point storage

##### Returns

int 0 if successful

Reimplemented from [interpolator\\_base](#).

### 5.36.4 Member Data Documentation

## 5.36.4.1 hypercube\_data

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
std::vector<hypercube_data_t> multilinear_static_gpu_interpolator2< index_t, value_t, N_DIMS,
N_OPS >::hypercube_data [protected]
```

static hypercube storage: the values of operators at every vertex of all hypercubes

In fact it is an excess storage used to reduce memory accesses during interpolation. Here all values of all vertexes of every hypercube are stored consecutively and are accessed via a single index Usage of point\_data for interpolation directly would require N\_VERTS memory accesses (>1000 accesses for 10-dimensional space)

## 5.36.4.2 point\_data

```
template<typename index_t , typename value_t , uint8_t N_DIMS, uint8_t N_OPS>
std::vector<point_data_t> multilinear_static_gpu_interpolator2< index_t, value_t, N_DIMS, N_OPS >::point_data
```

static point storage: the values of operators at all supporting points

Used to store all computed supporting points and to initialize hypercube\_data

## 5.37 pm::pm\_discretizer Class Reference

## Classes

- struct [Gradients](#)
- struct [InnerMatrices](#)

## Public Member Functions

- void **init** ()
- void **reconstruct\_gradients\_per\_cell** (value\_t dt)
- void **calc\_all\_fluxes** (value\_t dt)
- void **calc\_all\_fluxes\_once** (value\_t dt)

## Public Attributes

- std::vector< std::vector< [Face](#) > > **faces**
- std::vector< [Matrix33](#) > **perms**
- std::vector< [Matrix33](#) > **biots**
- std::vector< [Stiffness](#) > **stfs**
- std::vector< [Matrix](#) > **cell\_centers**
- std::vector< [Matrix](#) > **u0**
- std::vector< [Matrix](#) > **bc**
- std::vector< [Matrix](#) > **bc\_prev**
- std::vector< value\_t > **x\_prev**
- value\_t **visc**
- value\_t **grav**
- value\_t **density**

- [Matrix](#) **grav\_vec**
- `std::vector< index_t >` **cell\_m**
- `std::vector< index_t >` **cell\_p**
- `std::vector< index_t >` **stencil**
- `std::vector< index_t >` **offset**
- `std::vector< value_t >` **tran**
- `std::vector< value_t >` **rhs**
- `std::vector< value_t >` **tran\_biot**
- `std::vector< value_t >` **rhs\_biot**
- `std::vector< Gradients >` **grad**
- `std::vector< Gradients >` **grad\_prev**

### Static Public Attributes

- static const uint8\_t **MIN\_FACE\_NUM** = 4
- static const uint8\_t **MAX\_FACE\_NUM** = 8
- static const uint8\_t **BLOCK\_SIZE** = 4
- static const int **MAX\_STENCIL** = 15

### Protected Member Functions

- [Matrix](#) **get\_u\_face\_prev** (const [Matrix](#) &dr, const index\_t cell\_id) const
- [Matrix](#) **get\_ub\_prev** (const [Face](#) &face) const
- [Matrix](#) **calc\_grad\_prev** (const index\_t cell\_id) const
- [Matrix](#) **calc\_grad\_cur** (const index\_t cell\_id) const
- [Matrix](#) **calc\_vector** (const [Matrix](#) &a, const [Matrix](#) &rhs, const std::vector< index\_t > &stencil) const
- [Gradients](#) **merge\_stencils** (const std::vector< index\_t > &st1, const [Matrix](#) &m1, const std::vector< index\_t > &st2, const [Matrix](#) &m2)
- bool **check\_trans\_sum** (const std::vector< index\_t > &st, const [Matrix](#) &a) const
- void **write\_trans** (const std::vector< index\_t > &st, const [Matrix](#) &from)
- void **write\_trans\_biot** (const std::vector< index\_t > &st, const [Matrix](#) &from, const [Matrix](#) &from\_biot)
- std::pair< bool, size\_t > **findInVector** (const std::vector< index\_t > &vec, const index\_t &element)

### Protected Attributes

- int **n\_cells**
- int **n\_faces**
- int **nb\_faces**
- std::map< uint8\_t, [Matrix](#) > **pre\_A**
- std::map< uint8\_t, [Matrix](#) > **pre\_u1\_mult**
- std::map< uint8\_t, [Matrix](#) > **pre\_u2\_mult**
- std::map< uint8\_t, [Matrix](#) > **pre\_rest**
- std::map< uint8\_t, [Matrix](#) > **pre\_rhs\_mult**
- std::map< uint8\_t, std::map< uint8\_t, [Matrix](#) > > **pre\_cur\_rhs**
- [Matrix](#) **pre\_merged\_grad**
- std::vector< index\_t > **pre\_merged\_stencil**
- index\_t **st\_id**
- [Matrix](#) **W**
- std::vector< std::map< uint8\_t, [InnerMatrices](#) > > **inner**
- uint8\_t **counter**
- index\_t **id**
- std::vector< index\_t >::const\_iterator **it\_find**
- std::pair< bool, size\_t > **res1**
- std::pair< bool, size\_t > **res2**

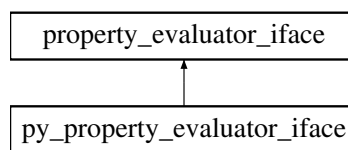
### Static Protected Attributes

- static const value\_t **darcy\_constant** = 0.0085267146719160104986876640419948
- static const [Matrix I3](#) = [pm::Matrix](#)({ 1,0,0, 0,1,0, 0,0,1 }, ND, ND)
- static const [Matrix I4](#) = [pm::Matrix](#)({ 1,0,0,0, 0,1,0,0, 0,0,1,0, 0,0,0,1 }, ND + 1, ND + 1)

## 5.38 property\_evaluator\_iface Class Reference

Virtual interface class for evaluation of physical properties values Implemented mainly by different C++ physical kernels from darts.physics However, pure Python implementation is also possible through inheritance.

Inheritance diagram for property\_evaluator\_iface:



### Public Member Functions

- virtual double [evaluate](#) (const std::vector< double > &state)=0  
*Compute property values for specified state.*
- int [evaluate](#) (const std::vector< double > &states, int n\_blocks, std::vector< double > &values)  
*Compute property values for all specified states A surrogate for vectorized evaluate function.*

#### 5.38.1 Detailed Description

Virtual interface class for evaluation of physical properties values Implemented mainly by different C++ physical kernels from darts.physics However, pure Python implementation is also possible through inheritance.

#### 5.38.2 Member Function Documentation

##### 5.38.2.1 [evaluate\(\)](#) [1/2]

```
virtual double property_evaluator_iface::evaluate (
    const std::vector< double > & state ) [pure virtual]
```

Compute property values for specified state.

#### Parameters

<code>state</code>	Coordinates in parameter space, where operators to be evaluated
--------------------	---

**Returns**

double property value

Implemented in [py\\_property\\_evaluator\\_iface](#).

**5.38.2.2 evaluate()** [2/2]

```
int property_evaluator_iface::evaluate (
    const std::vector< double > & states,
    int n_blocks,
    std::vector< double > & values ) [inline]
```

Compute property values for all specified states A surrogate for vectorized evaluate function.

**Parameters**

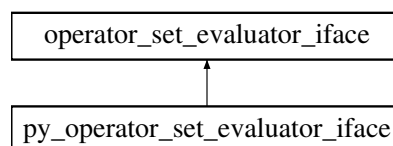
in	<i>states</i>	array of states
in	<i>n_blocks</i>	the number of states
out	<i>values</i>	evaluated property values

**Returns**

int

**5.39 py\_operator\_set\_evaluator\_iface Class Reference**

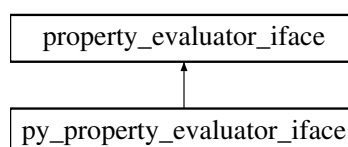
Inheritance diagram for py\_operator\_set\_evaluator\_iface:

**Public Member Functions**

- int **evaluate** (const std::vector< value\_t > &state, std::vector< value\_t > &values)

**5.40 py\_property\_evaluator\_iface Class Reference**

Inheritance diagram for py\_property\_evaluator\_iface:



## Public Member Functions

- `value_t evaluate` (const std::vector< value\_t > &state)  
*Compute property values for specified state.*
- `int evaluate` (const std::vector< value\_t > &states, index\_t n\_blocks, std::vector< value\_t > &values)

### 5.40.1 Member Function Documentation

#### 5.40.1.1 evaluate()

```
value_t py_property_evaluator_iface::evaluate (
    const std::vector< value_t > & state ) [inline], [virtual]
```

Compute property values for specified state.

#### Parameters

<code>state</code>	Coordinates in parameter space, where operators to be evaluated
--------------------	---

#### Returns

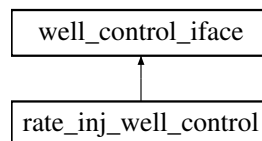
double property value

Implements [property\\_evaluator\\_iface](#).

## 5.41 rate\_inj\_well\_control Class Reference

Volumetric rate control for injection compositional well.

Inheritance diagram for rate\_inj\_well\_control:



## Public Member Functions

- **rate\_inj\_well\_control** (std::vector< std::string > phase\_names\_, index\_t target\_phase\_idx\_, index\_t n\_equations\_, index\_t n\_variables\_, value\_t target\_rate\_, std::vector< value\_t > &injection\_stream\_, operator\_set\_gradient\_evaluator\_iface \*rate\_etor\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **add\_to\_csr\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

## Public Attributes

- `index_t target_phase_idx`
- `index_t n_equations`
- `index_t n_variables`
- `std::vector< std::string > phase_names`
- `value_t target_rate`
- `std::vector< value_t > injection_stream`
- `operator_set_gradient_evaluator_iface * rate_eter`
- `std::vector< value_t > state`
- `std::vector< value_t > rates`
- `std::vector< value_t > rates_derivs`

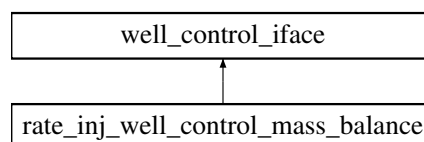
### 5.41.1 Detailed Description

Volumetric rate control for injection compositional well.

## 5.42 rate\_inj\_well\_control\_mass\_balance Class Reference

Rate control based on mass balance equation for injection compositional well.

Inheritance diagram for `rate_inj_well_control_mass_balance`:



## Public Member Functions

- **rate\_inj\_well\_control\_mass\_balance** (`std::vector< std::string > phase_names_`, `index_t target_phase_idx_`, `index_t n_equations_`, `index_t n_variables_`, `value_t target_rate_`, `std::vector< value_t > &injection_stream_`, `operator_set_evaluator_iface *rate_eter_`, `operator_set_gradient_evaluator_iface *sources_eter_`)
- virtual `int add_to_jacobian` (`value_t dt`, `index_t well_head_idx`, `value_t segment_trans`, `index_t n_block_size`, `std::vector< value_t > &X`, `value_t *jacobian_row`, `std::vector< value_t > &RHS`)
- virtual `int check_constraint_violation` (`value_t dt`, `index_t well_head_idx`, `value_t segment_trans`, `index_t n_block_size`, `std::vector< value_t > &X`)
- virtual `int initialize_well_block` (`std::vector< value_t > &state_block`, `const std::vector< value_t > &state_neighbour`)

## Public Attributes

- `index_t target_phase_idx`
- `index_t n_equations`
- `index_t n_variables`
- `std::vector< std::string > phase_names`
- `value_t target_rate`
- `std::vector< value_t > injection_stream`
- `operator_set_gradient_evaluator_iface * sources_eter`
- `operator_set_evaluator_iface * rate_eter`
- `std::vector< value_t > state`
- `std::vector< value_t > sources`
- `std::vector< value_t > rates`
- `std::vector< value_t > sources_derivs`

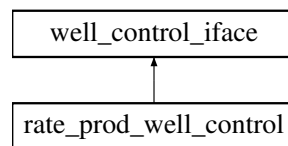
### 5.42.1 Detailed Description

Rate control based on mass balance equation for injection compositional well.

## 5.43 rate\_prod\_well\_control Class Reference

Volumetric rate control for production compositional well.

Inheritance diagram for rate\_prod\_well\_control:



### Public Member Functions

- **rate\_prod\_well\_control** (std::vector< std::string > phase\_names\_, index\_t target\_phase\_idx\_, index\_t n\_↵\_equations\_, index\_t n\_variables\_, value\_t target\_rate\_, operator\_set\_gradient\_evaluator\_iface \*rate\_eto↵\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_↵\_neighbour)

### Public Attributes

- index\_t **target\_phase\_idx**
- index\_t **n\_equations**
- index\_t **n\_variables**
- std::vector< std::string > **phase\_names**
- value\_t **target\_rate**
- operator\_set\_gradient\_evaluator\_iface \* **rate\_eto**
- std::vector< value\_t > **state**
- std::vector< value\_t > **rates**
- std::vector< value\_t > **rates\_derivs**

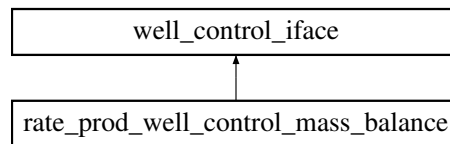
### 5.43.1 Detailed Description

Volumetric rate control for production compositional well.

## 5.44 rate\_prod\_well\_control\_mass\_balance Class Reference

Rate control based on mass balance equation for production compositional well.

Inheritance diagram for rate\_prod\_well\_control\_mass\_balance:



### Public Member Functions

- **rate\_prod\_well\_control\_mass\_balance** (std::vector< std::string > phase\_names\_, index\_t target\_phase\_idx\_, index\_t n\_equations\_, index\_t n\_variables\_, value\_t target\_rate\_, operator\_set\_evaluator\_iface \*rate\_eter\_, operator\_set\_gradient\_evaluator\_iface \*sources\_eter\_)
- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)

### Public Attributes

- index\_t **target\_phase\_idx**
- index\_t **n\_equations**
- index\_t **n\_variables**
- std::vector< std::string > **phase\_names**
- value\_t **target\_rate**
- operator\_set\_gradient\_evaluator\_iface \* **sources\_eter**
- operator\_set\_evaluator\_iface \* **rate\_eter**
- std::vector< value\_t > **state**
- std::vector< value\_t > **sources**
- std::vector< value\_t > **rates**
- std::vector< value\_t > **sources\_derivs**

#### 5.44.1 Detailed Description

Rate control based on mass balance equation for production compositional well.

## 5.45 sim\_params Class Reference

Main simulation parameters including tolerances.

## Public Types

- enum **newton\_solver\_t** { **NEWTON\_STD** = 0, **NEWTON\_GLOBAL\_CHOP**, **NEWTON\_LOCAL\_CHOP**, **NEWTON\_INFLECTION\_POINT** }
- enum **linear\_solver\_t** { **CPU\_GMRES\_CPR\_AMG** = 0, **CPU\_GMRES\_CPR\_AMG1R5**, **CPU\_GMRES\_FS\_CPR**, **CPU\_GMRES\_ILU0**, **CPU\_SUPERLU**, **GPU\_GMRES\_CPR\_AMG**, **GPU\_GMRES\_ILU0**, **GPU\_GMRES\_CPR\_AIPS**, **GPU\_GMRES\_CPR\_AMGX\_ILU**, **GPU\_GMRES\_CPR\_AMGX\_ILU\_SP**, **GPU\_GMRES\_CPR\_AMGX\_AMGX**, **GPU\_GMRES\_AMGX**, **GPU\_AMGX**, **GPU\_GMRES\_CPR\_NF**, **GPU\_BICGSTAB\_CPR\_AMGX** }
- enum **nonlinear\_norm\_t** { **L1** = 0, **L2**, **LINF** }

## Public Attributes

- value\_t **first\_ts**
- value\_t **max\_ts**
- value\_t **mult\_ts**
- index\_t **max\_i\_newton**
- index\_t **min\_i\_newton**
- index\_t **max\_i\_linear**
- value\_t **tolerance\_newton**
- value\_t **tolerance\_linear**
- index\_t **tot\_newt\_count**
- index\_t **log\_transform**
- index\_t **interface\_avg\_tmult**
- index\_t **trans\_mult\_exp**
- value\_t **obl\_min\_fac**
- int **assembly\_kernel**
- newton\_solver\_t **newton\_type**
- linear\_solver\_t **linear\_type**
- nonlinear\_norm\_t **nonlinear\_norm\_type**
- std::vector< value\_t > **newton\_params**
- std::vector< value\_t > **linear\_params**
- std::vector< int > **global\_actnum**

### 5.45.1 Detailed Description

Main simulation parameters including tolerances.

## 5.46 sim\_stat Class Reference

Main simulation statistics with active and wasted counts.

## Public Attributes

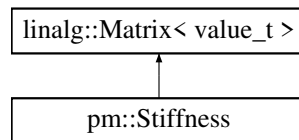
- index\_t **n\_newton\_total**
- index\_t **n\_linear\_total**
- index\_t **n\_newton\_wasted**
- index\_t **n\_linear\_wasted**
- index\_t **n\_timesteps\_total**
- index\_t **n\_timesteps\_wasted**

### 5.46.1 Detailed Description

Main simulation statistics with active and wasted counts.

## 5.47 pm::Stiffness Class Reference

Inheritance diagram for pm::Stiffness:



### Public Types

- typedef [Matrix](#) **Base**

### Public Member Functions

- **Stiffness** (value\_t la, value\_t mu)
- **Stiffness** (std::valarray< value\_t > \_c)

### Static Public Attributes

- static const index\_t **N** = SUM\_N(ND) \* SUM\_N(ND)

### Additional Inherited Members

## 5.48 well\_control Struct Reference

Structure for well control.

### Public Member Functions

- [well\\_control](#) ()  
*temperature of injection stream*

### Public Attributes

- int **control\_type**
- value\_t [control\\_param](#)  
*INJECTOR\_BHP or PRODUCER\_BHP.*
- std::vector< value\_t > [inj\\_stream](#)  
*BHP (or rate) value.*
- value\_t [inj\\_temperature](#)  
*composition of injection stream*

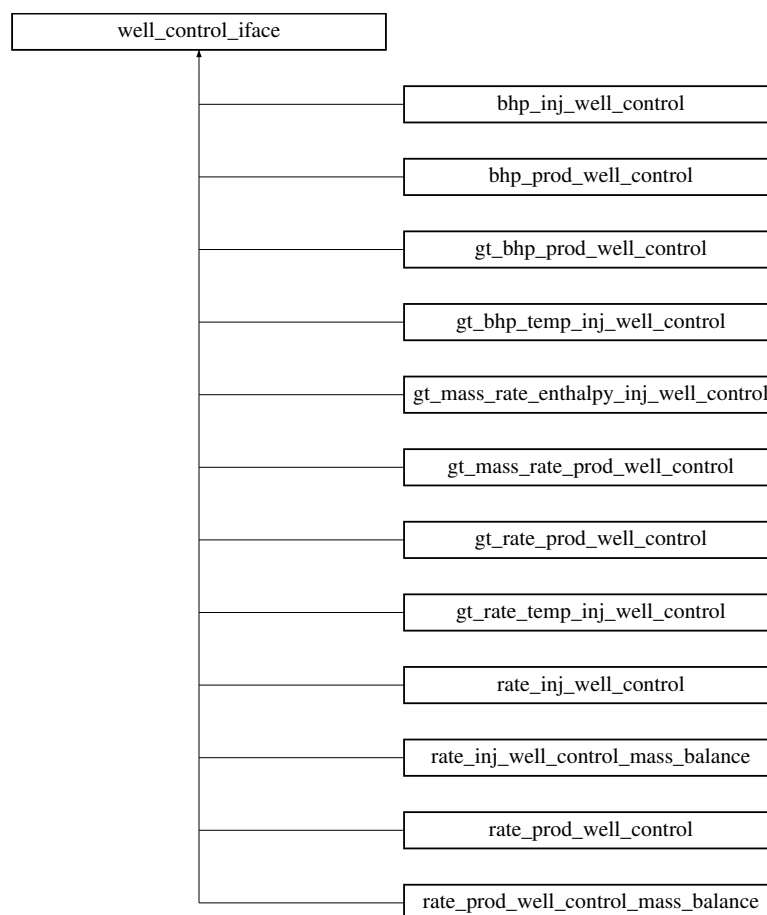
### 5.48.1 Detailed Description

Structure for well control.

## 5.49 well\_control\_iface Class Reference

Base class work well control/constraint.

Inheritance diagram for well\_control\_iface:



### Public Member Functions

- virtual int **add\_to\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)=0
- virtual int **check\_constraint\_violation** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X)=0
- virtual int **initialize\_well\_block** (std::vector< value\_t > &state\_block, const std::vector< value\_t > &state\_neighbour)=0
- virtual int **add\_to\_csr\_jacobian** (value\_t dt, index\_t well\_head\_idx, value\_t segment\_trans, index\_t n\_block\_size, std::vector< value\_t > &X, value\_t \*jacobian\_row, std::vector< value\_t > &RHS)

### Public Attributes

- `std::string` **name**
- `std::vector< index_t >` **block\_idx**

#### 5.49.1 Detailed Description

Base class work well control/constraint.